

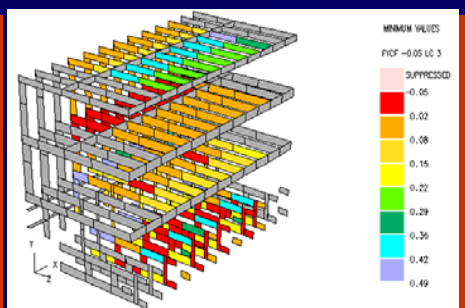
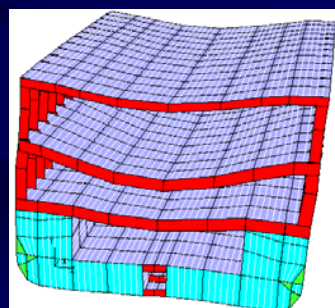
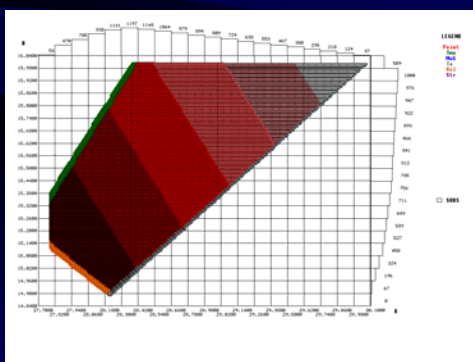
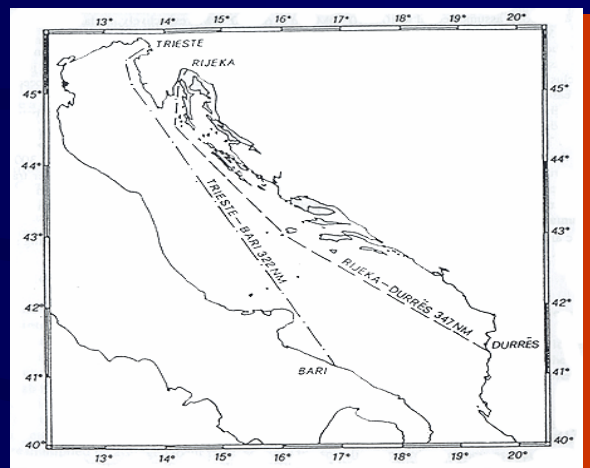
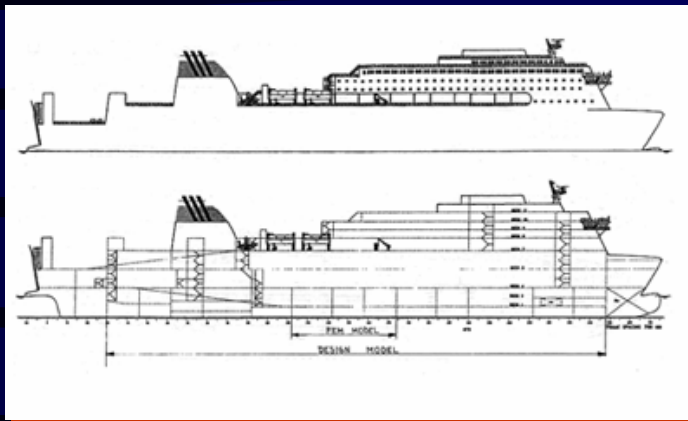
L4c

SUMMARY ON STRUCTURAL DESIGN METHODS and CASE STUDIES

1. DESIGN PROBLEM FORMULATION
 2. DESIGN PROBLEM SOLUTION
 3. APPLICATIONS
- CONCLUSIONS

V. Zanic - Optimization of Thin-Walled Structures

1. DESIGN PROBLEM FORMULATION



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DESIGN PHASES

- ❑ Concept design
- ❑ Reliability-based design
- ❑ Preliminary design

using :

- multi-criteria decision making techniques
- design space exploration via Pareto frontier (non-dominated designs)
- development of new macroelements and ultimate strength failure criteria
- development of integrated design procedures

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SOFTWARE USED IN EXAMPLES

TORO 1979 ... / (FEM shear flow analysis in bending and torsion) at Zagreb Uni.

MAESTRO/SHIPOPT 1975 ...2006 / (FEM analysis + synthesis) with Profs. O.F.Hughes and F. Mistree for ABS and later for PROTEUS Eng. USA.

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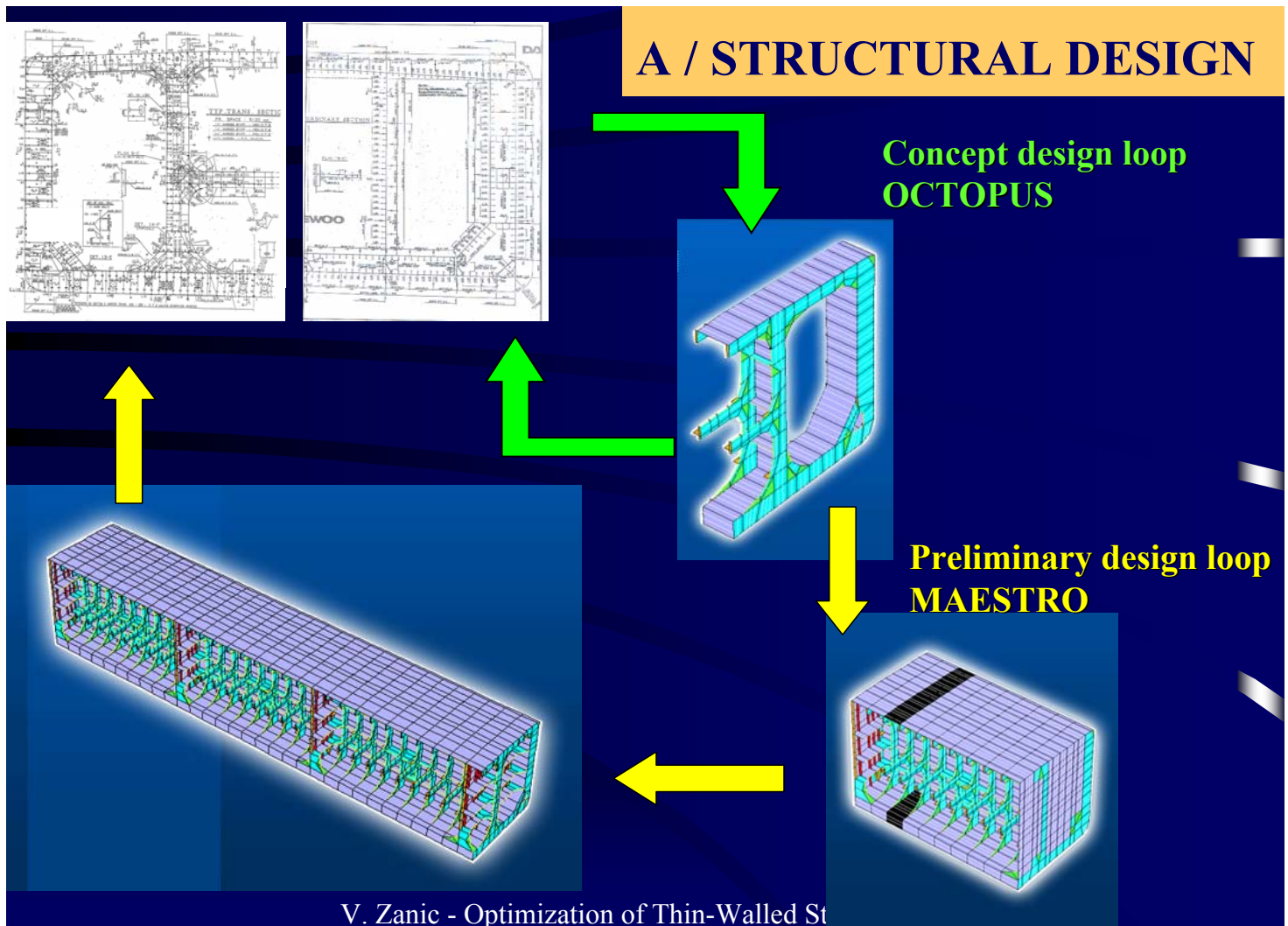
SOFTWARE (cont.)

OCTOPUS 1990 ...2006 / (FEM analysis, reliability based design) at Zagreb and Glasgow Uni.

CREST 1999 ... 2006 / (OCTOPUS integrated, FEM analysis, Croatian Register Rules, **IACS CSR (T)**)

DEMAK 1990 ...2006 / (Synthesis using multicriterial decision making) at Zagreb Uni.

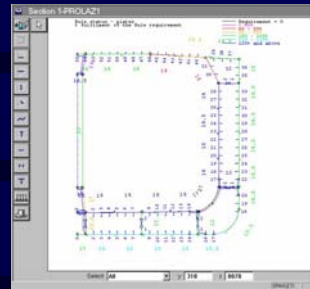
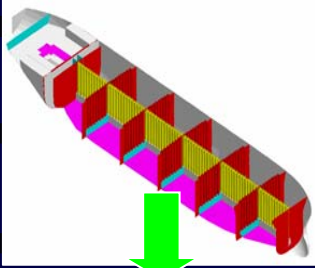
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CONCEPT DESIGN

TRIDENT

TRIDENT
COMPARTMENTATION



CLASS, SOC,
RULE PROGRAMS

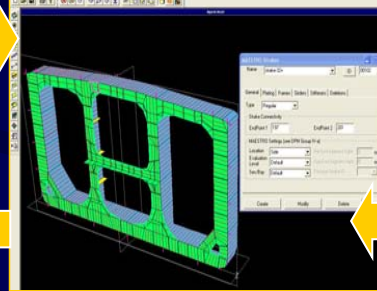
eg. IACS
CSR for
tankers

OCTOPUS

OCTOPUS ANALYZER

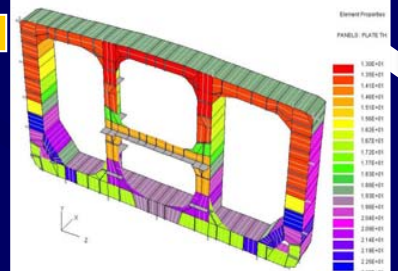


TRIDENT/FEM
MODELER

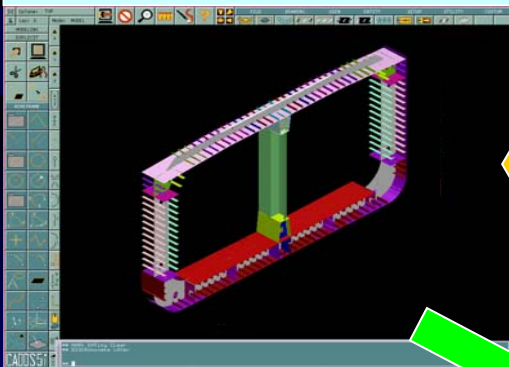


- FRAME SPACING
- SCANTLING OPTIMIZATION
-

OCTOPUS DESIGNER



TRIDENT
HULL STRUCTURE



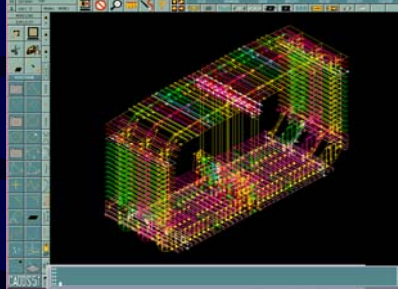
WEIGHT ESTIMATES

CLASS MODEL

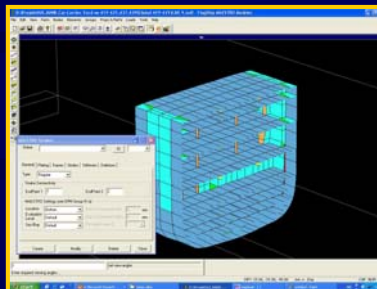
V. Zanic - Optimization of Thin-walled Structures

PRELIMINARY DESIGN

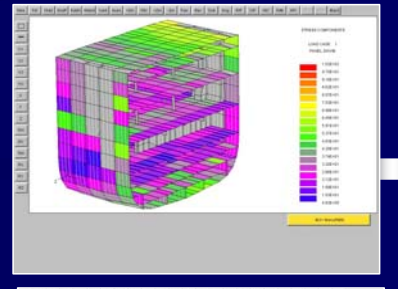
HULL MODELLING



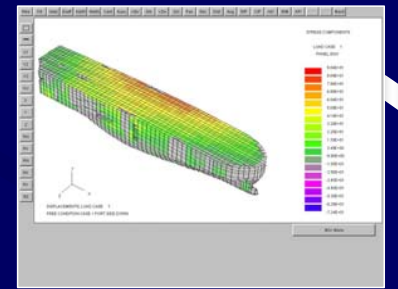
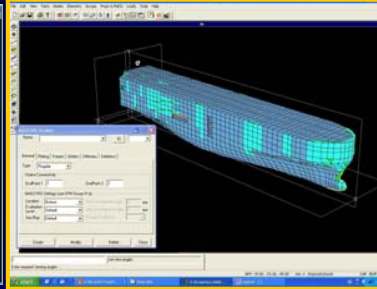
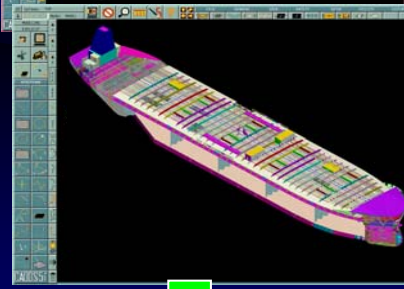
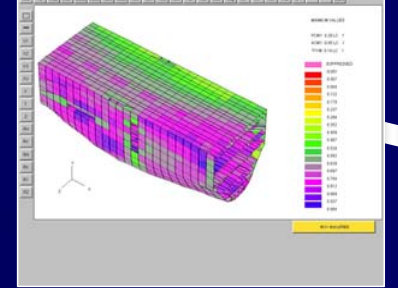
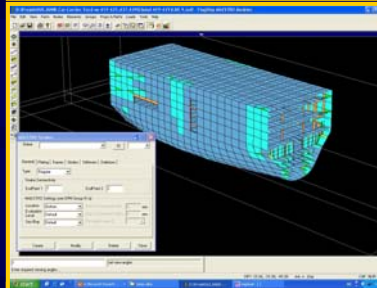
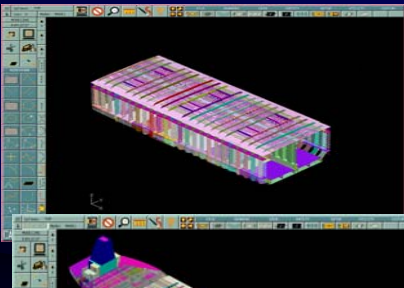
FEM MODELER



FEM SOLVER - MAESTRO



HULL CLASS
MODEL



CLASS DRAWINGS, PRODUCTION MODEL

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CONCEPT DESIGN ANALYSIS SYSTEM

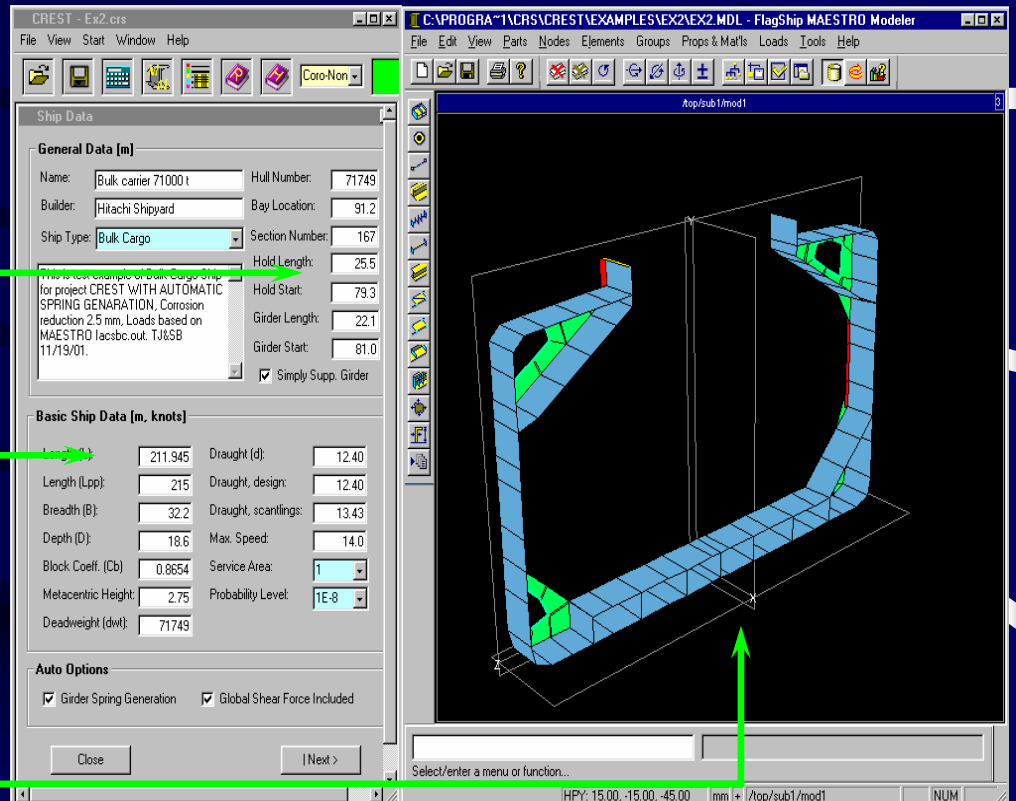
OCTOPUS ANALYZER:

Workspace

MODEL GENERAL DATA

BASIC SHIP DATA

MODEL FIGURE



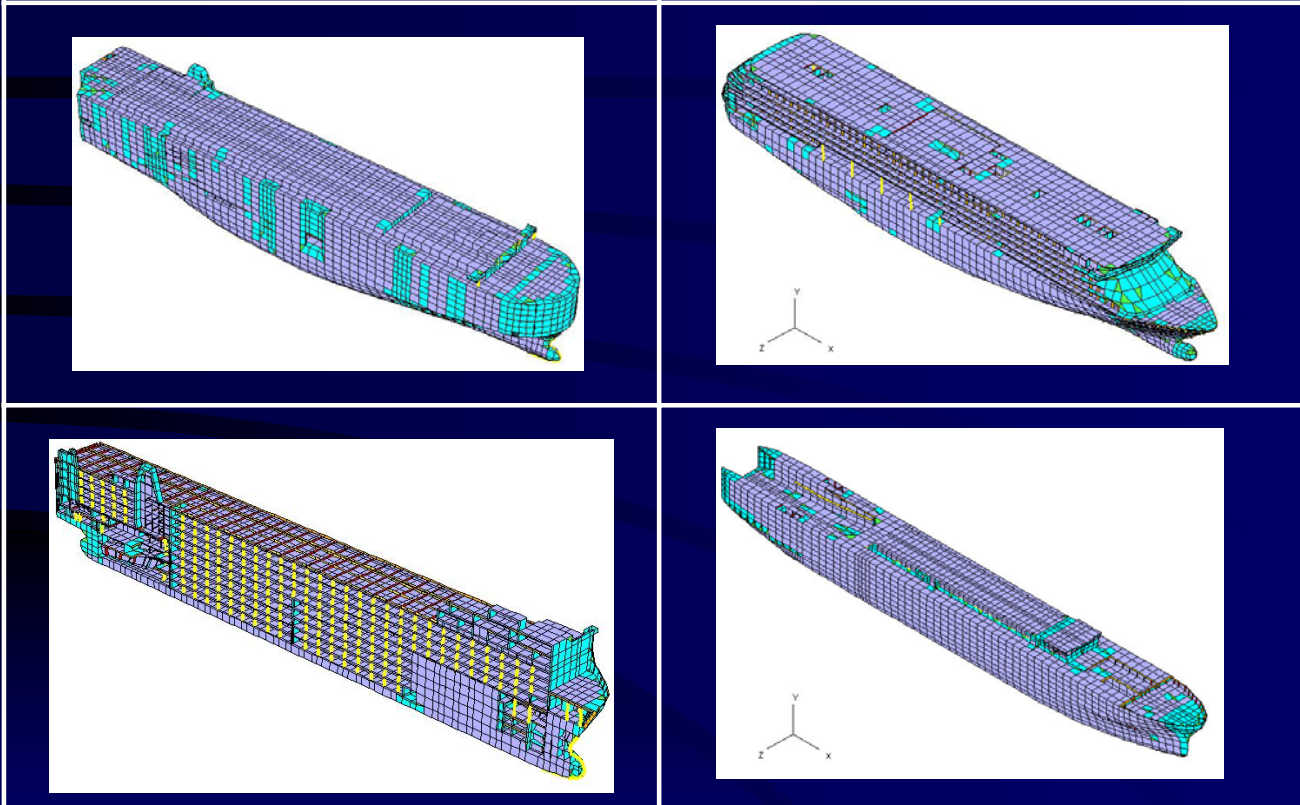
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ANALYSIS MODULES

ANALYSIS MODELS	OCTOPUS ANALYZER MODULES
Physical (Φ)	FEM STRUCTURAL MODELER MIND – generator of minimal dimensions
Environment (ϵ)	OCTLOAD - load model
Response ($\rho-1$)	LTOR- primary strength fields (warping displac.; normal/shear stresses)
Response ($\rho-2$)	TOKV -secondary strength fields: transverse and lateral displacements, stresses
Adequacy / feasibility ($\alpha-1$)	EPAN – library of stiffened panel and girder ultimate strength & serviceability criteria. (FATCS – Rules fatigue calculation-Level 1)
Adequacy ($\alpha-2$)	LUSA – Ultimate longitudinal strength module
Reliability ($\pi-1,2$)	US-3 reliability calculation of element and system failure probability (level 1-3, mechan.) SENCOR – sensitivity to correlation.
Quality ($\Omega-1$ to 8)	WST / INC - cost/weight DCLV - ultimate vertical bending moment DCLT- ultimate racking load SSR / SCR - reliability measures ICM / TSN - robustness measures

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FMENA data base for calibration of mathematical models of thin-walled structures



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PHYSICAL (Φ): - FEM STRUCTURAL MODELER, - MINIMAL DIMENSIONS MODULE

Ship Data

General Data [m]

Name:	ROPAX	Hull Number:	1
Builder:	BRDDOSPLIT	Bay Location:	102.9
Ship Type:	Passenger	Section Number:	1
		Hold Length:	11.2
		Hold Start:	97.3
		Girder Length:	11.2
		Girder Start:	97.3
		<input checked="" type="checkbox"/> Simply Supp. Girder	

Basic Ship Data [m, knots]

Length (L):	215	Draught (d):	10.0
Length (Lpp):	207	Draught, design:	10.0
Breadth (B):	29.4	Draught, scantlings:	10.4
Depth (D):	22.8	Max. Speed:	24.5
Block Coeff. (Cb):	0.68	Service Area:	1
Metacentric Height:	0.5	Probability Level:	1E-8
Deadweight (dwt):	28000		

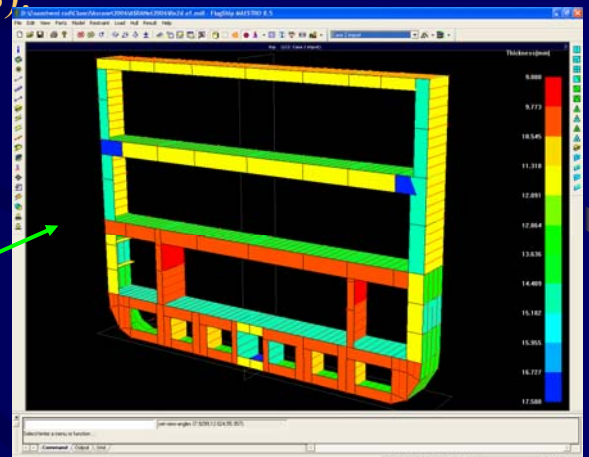
Auto Options

Girder Spring Generation Global Shear Force Included

Close | Next >

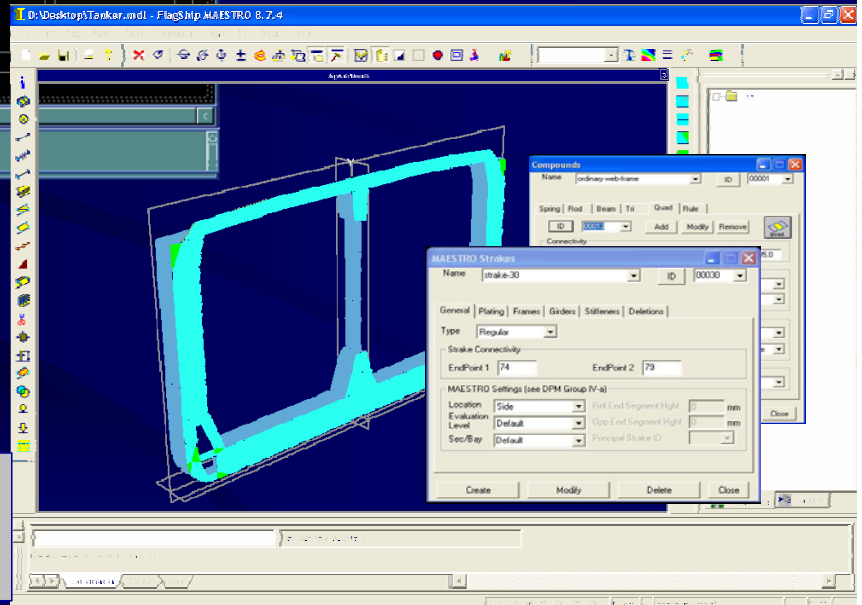
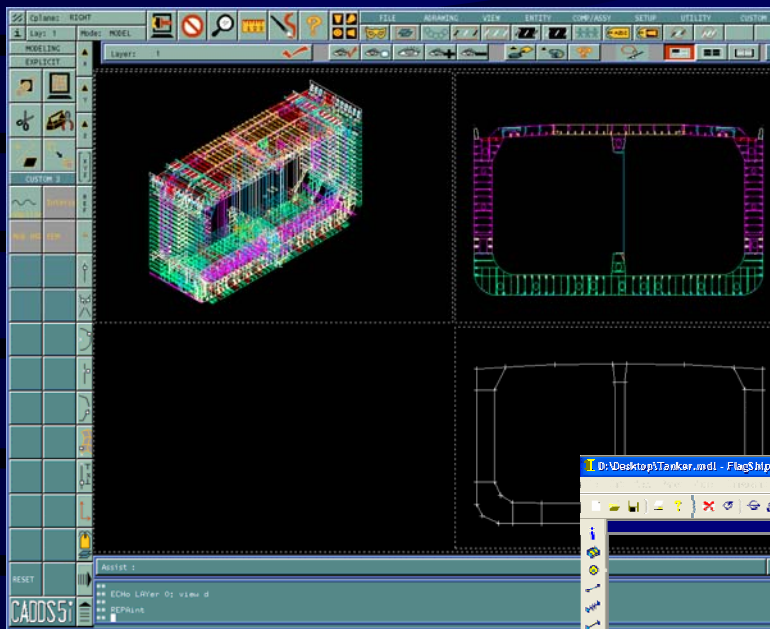
- MAESTRO MODELER used to define 2.5D FEM model with different cross-sections (web-frame, bulkhead).
- MIND (minimal dimensions definition from Class. Society Rules-eg. IACS CSR for tankers)

RoPax



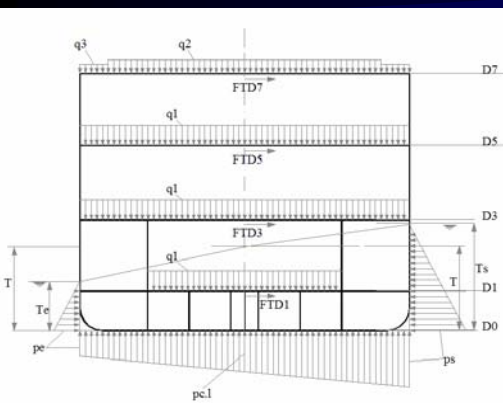
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INTERACTIVE XML DATA GENERATION IN CAD TRIDENT MODEL FOR OCTOPUS FEM MODEL.



INTERACTIVE FEM MODEL DEVELOPMENT BASED ON XML TRIDENT DATA

ENVIRONMENT (ϵ): - OCTLOAD



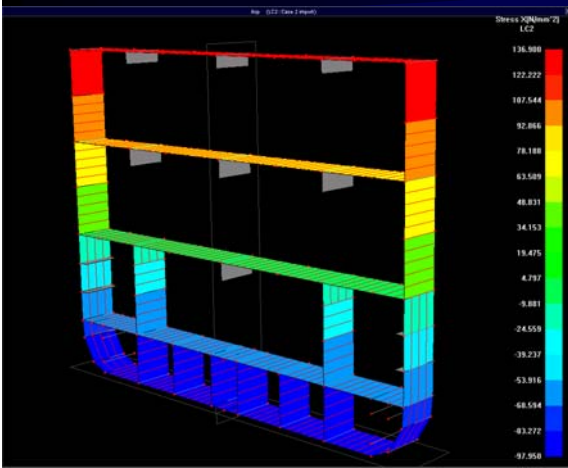
- **Class. Society Loads** - DNV (Note: CRS and IACS -CSR are generated automatically - CREST software).
- **Designer given loads** from seakeeping analysis (3D Hydro model) are optional input.

LC 6 and 7

RoPax

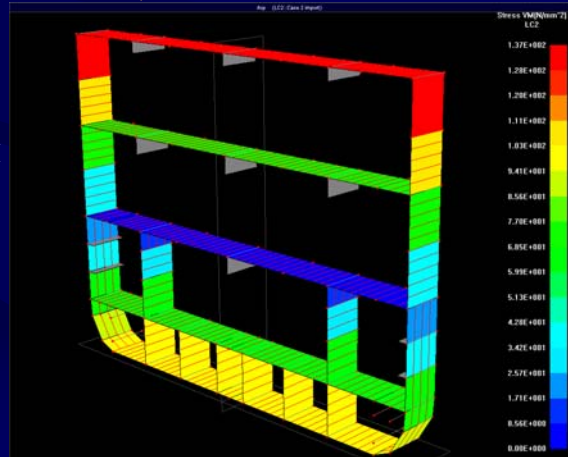
LC	DESCRIPTION
1-SAGG	Full load on decks + dyn. / Scantling draught
2-HOGG	Full load on decks + dyn. / Scantling draught
3-SAGG	Full load on decks except D1 + dyn. / T- scantling
4-HOGG	Full load on decks except D1 + dyn. / T- scantling
5-HOGG	Ballast condition / Draught 5.8 m
6-SAGG	Full load on decks + dyn. / Heeled condition
7-HOGG	Full load on decks + dyn. / Heeled condition

RESPONSE ($\rho - 1$): - LTOR

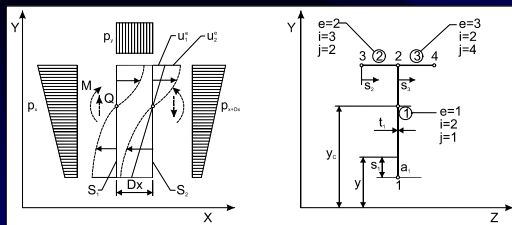


LC 2 - σ_x

- Primary strength fields
 - Warping displ.; normal/shear stresses
 - Extended beam theory (cross section warping fields via FEM in vertical / horizontal bending and warping torsion)

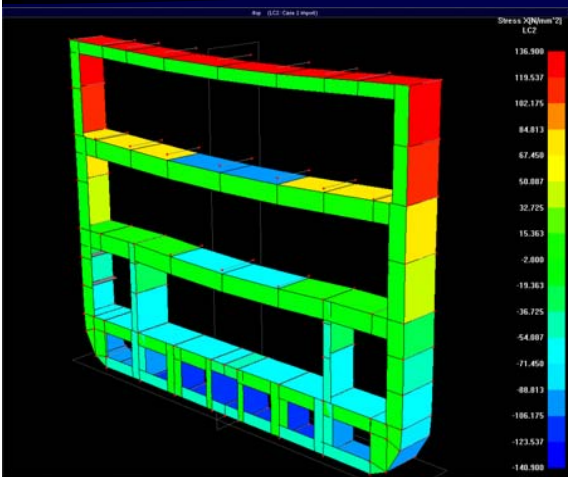


LC 2 - σ_{VM}



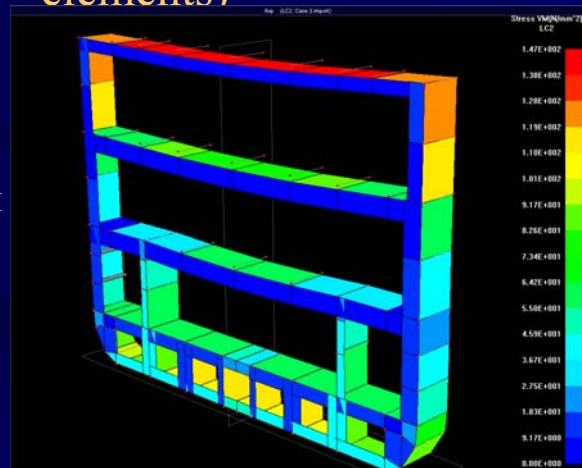
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RESPONSE ($\rho - 2$): - TOKV

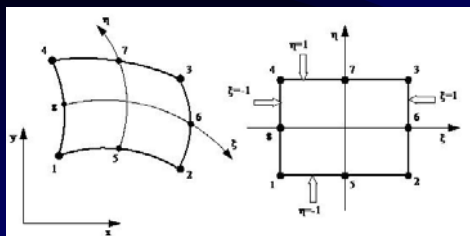


LC 2 - σ_x

- Secondary strength fields:
 - transverse and lateral displ.; stresses
 - FEM analysis of web-frame and bulkhead (beam element with rigid ends; stiffened shell 8-node macro-elements)



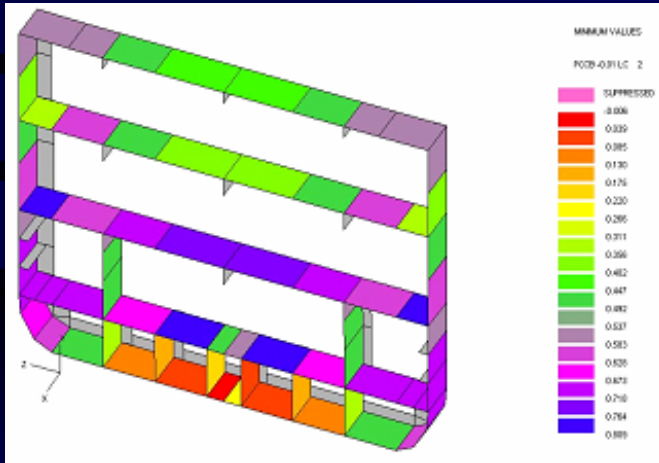
LC 2 - σ_{VM}



V. Zanic - Optimization of Thin-Walled Structures

ADEQUACY ($\alpha-1$): - EPAN / ELAN(IACS CSR)

- Library of stiffened panel and girder ultimate strength & serviceability criteria
 - Calculation of macroelement feasibility based on super-position of response fields $\rho-1$, $\rho-2$ (FEM); $\rho-3$ (analytical) and using the library of analytical safety criteria

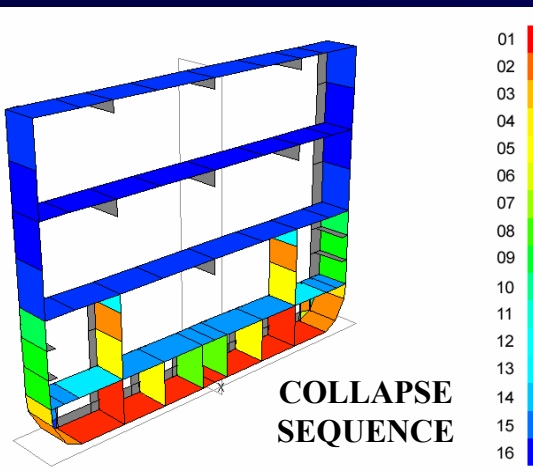


$$-1 \leq g(x) = \frac{C - SF \cdot D}{C + SF \cdot D} \leq 1,$$

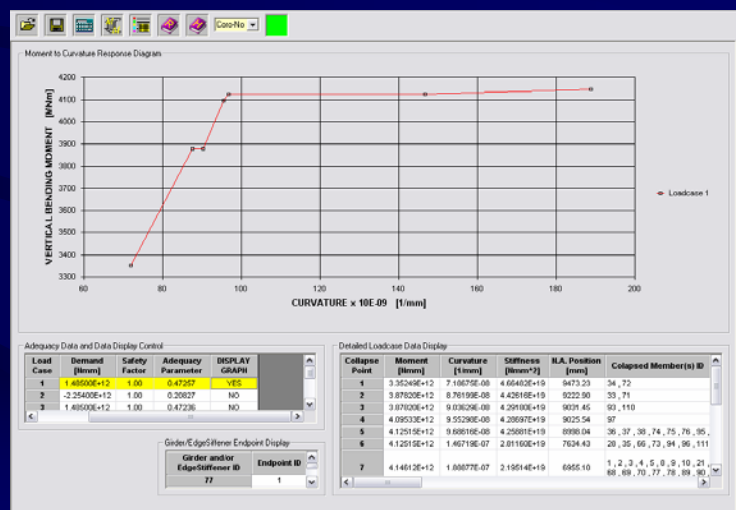
NAME	CRITERIA DESCRIPTION - PLATE
PCMY	Panel Collapse Membrane Yield (Von Misses)
PYLS	Panel Yield Longitudinal Strength
PCAPS	Panel Collapse Arched Plate Yield
PCAPT	Panel Collapse Arched Plate Shear
PFLB	Panel Failure. Local Buckling
PCES	Panel Collapse Edge Shear
S-UCS	SLS, Uniaxial Compressive Stress
U-UCS	ULS, Uniaxial Compressive Stress
S-ES	SLS, Edge Shear
U-ES	ULS, Edge Shear
S-ULL	SLS, Uniform Lateral Load
U-ULL	ULS, Uniform Lateral Load
.....

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ADEQUACY ($\alpha-2$): - LUSA-1,2,3



- Ultimate longitudinal strength
 - Incremental ultimate strength analysis of cross-section using IACS and extended Hughes/Adamchak procedures



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RELIABILITY ($\pi-1$): - US3

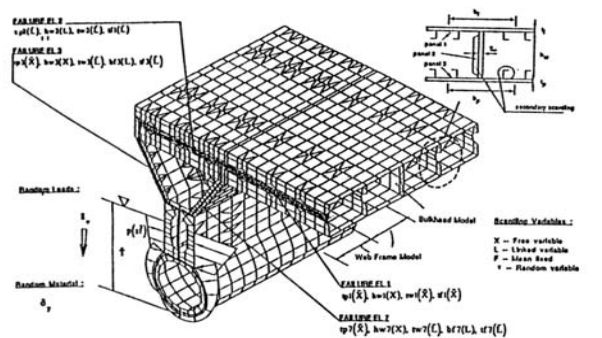
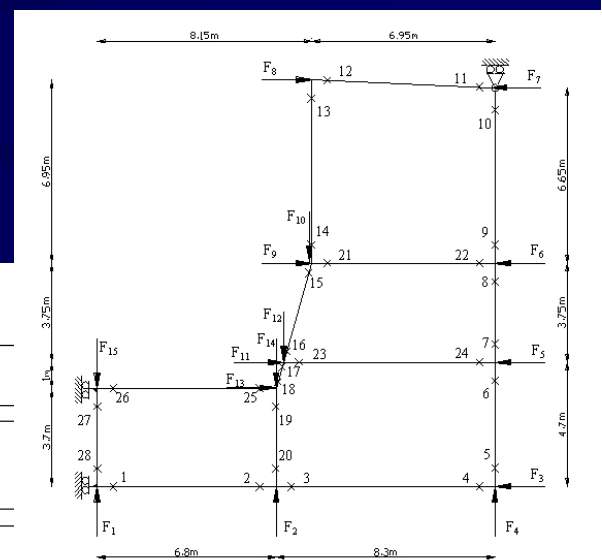
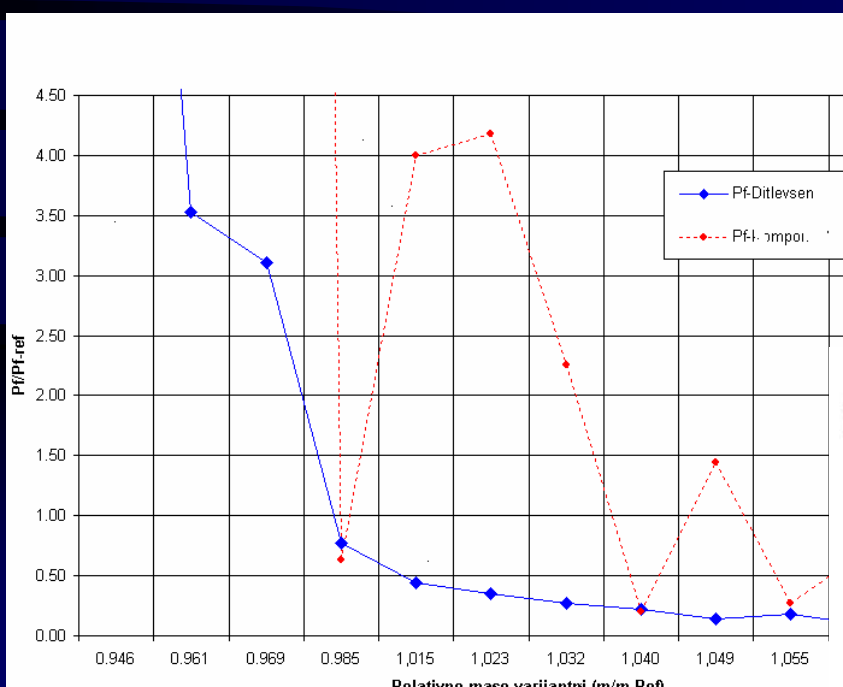
System failure probability based upon β -unzipping method for system probability of failure

- Probabilistically dominant collapse scenarios are selected from the (large) set of potential collapse scenarios at the first, second, third and mechanism level.
- The system reliability measure at third level (RM-3) was found sufficient for the optimization (design) purpose.
- RM-3 is modeled as a series system of all identified, probabilistically dominant collapse scenarios.

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RELMOD

Pareto frontier :
normalised mass vs. normalised P_f



ROBEX

Robustness Analysis by Fractional Factorial Experiments

Robustness is the sensitivity to uncertain (uncontrolable) parametrs. A metric developed by **Taguchi** is the ratio of

- **mean of the attribute value (μ)**, resulting from the values of design variables, to
- variation resulting from uncertain parameter values measured via **standard deviation (σ)**.

$$SN_n = 20 \log(\mu / \sigma) = 10 \log(\mu^2 / \sigma^2) = 10[\log(\mu^2 / \sigma^2)]$$

It is the ratio of predictability versus unpredictability.

SN = robustness attribute in multi-criterial design

The most robust design coresponds to max SN.

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QUALITY (Ω): DESIGN ATTRIBUTES

- **INC - cost module**
 - Minimal initial cost
- **WST - weight module**
 - Minimal structural weight = maximal DWT increase
- **DCLV - ultimate vertical bending moment**
 - Calculations using LUSA
- **SSR / SCR - reliability measures (maintenance, risk analysis)**
 - Upp. Ditlevsen bound of panel failure/ racking failure probab.
- **ICM / TSN - robustness measures**
 - (Information context measure / Taguchi S/N ratio via FFE).

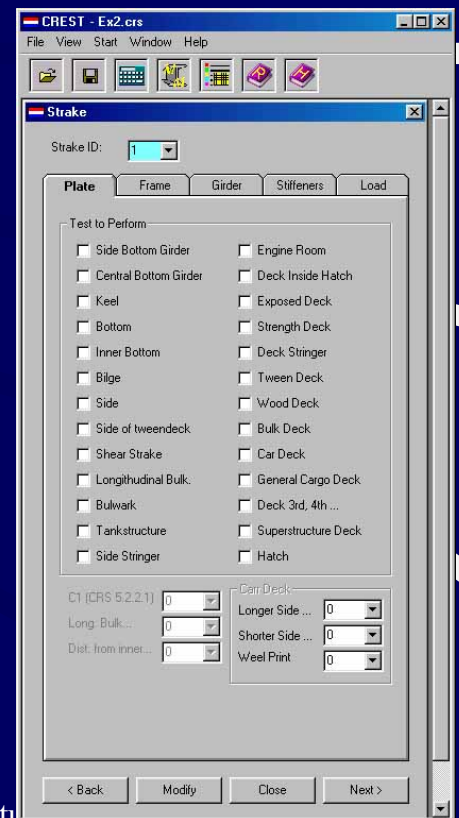
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CSMIND

Minimal dimensions verification according to IACS Rules

- Calculation of minimal structural element dimensions according to CS descriptors
- Comparison of the as built and required dimensions
- Verification of a corroded element dimensions

Selection of CS tests for strake plating →



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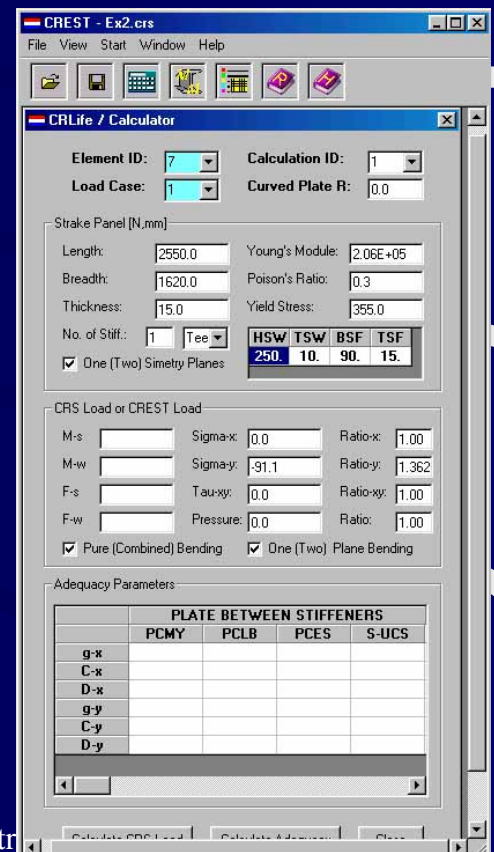
CALCULATOR

Criteria recalculation for new element dimensions

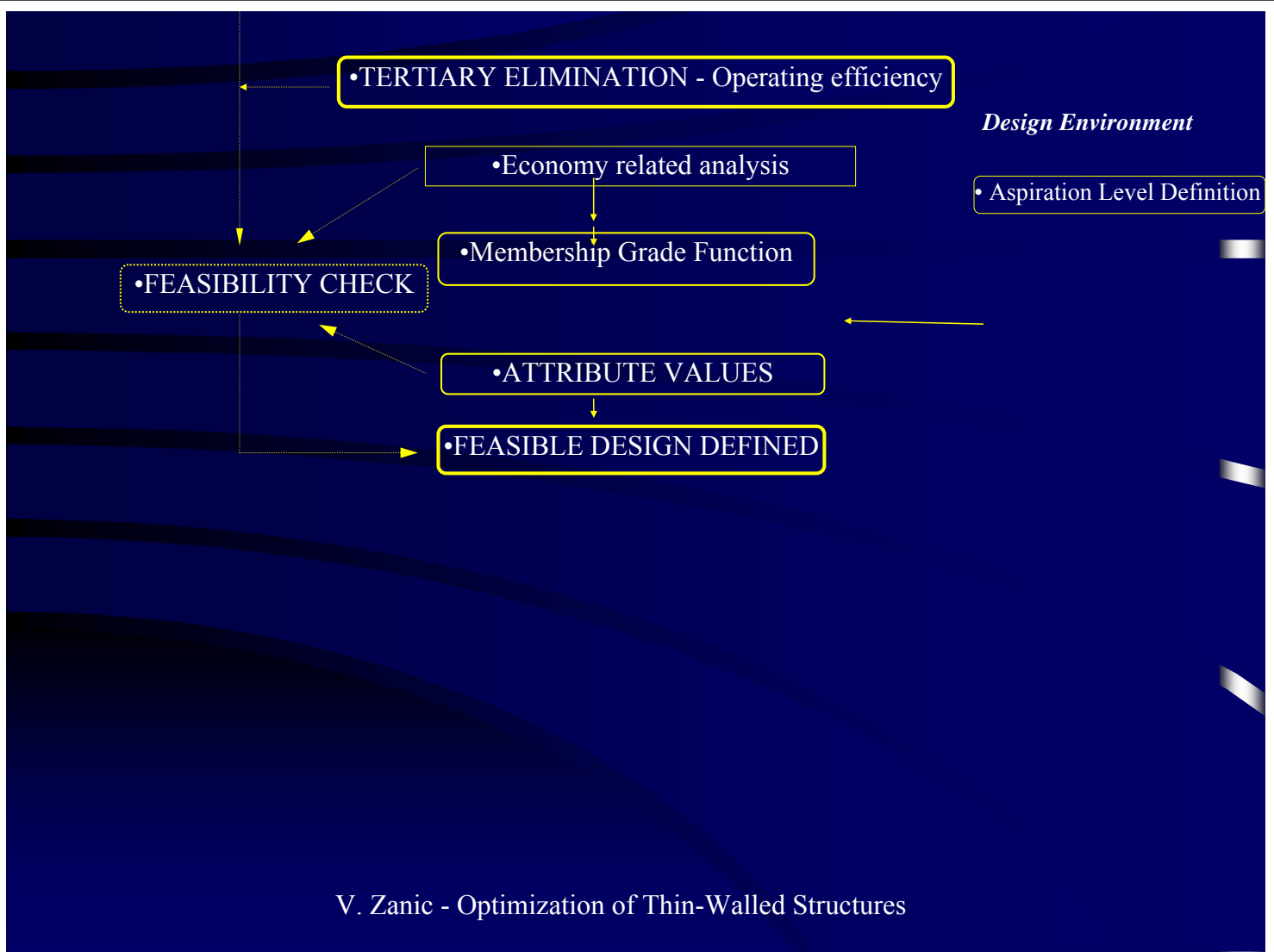
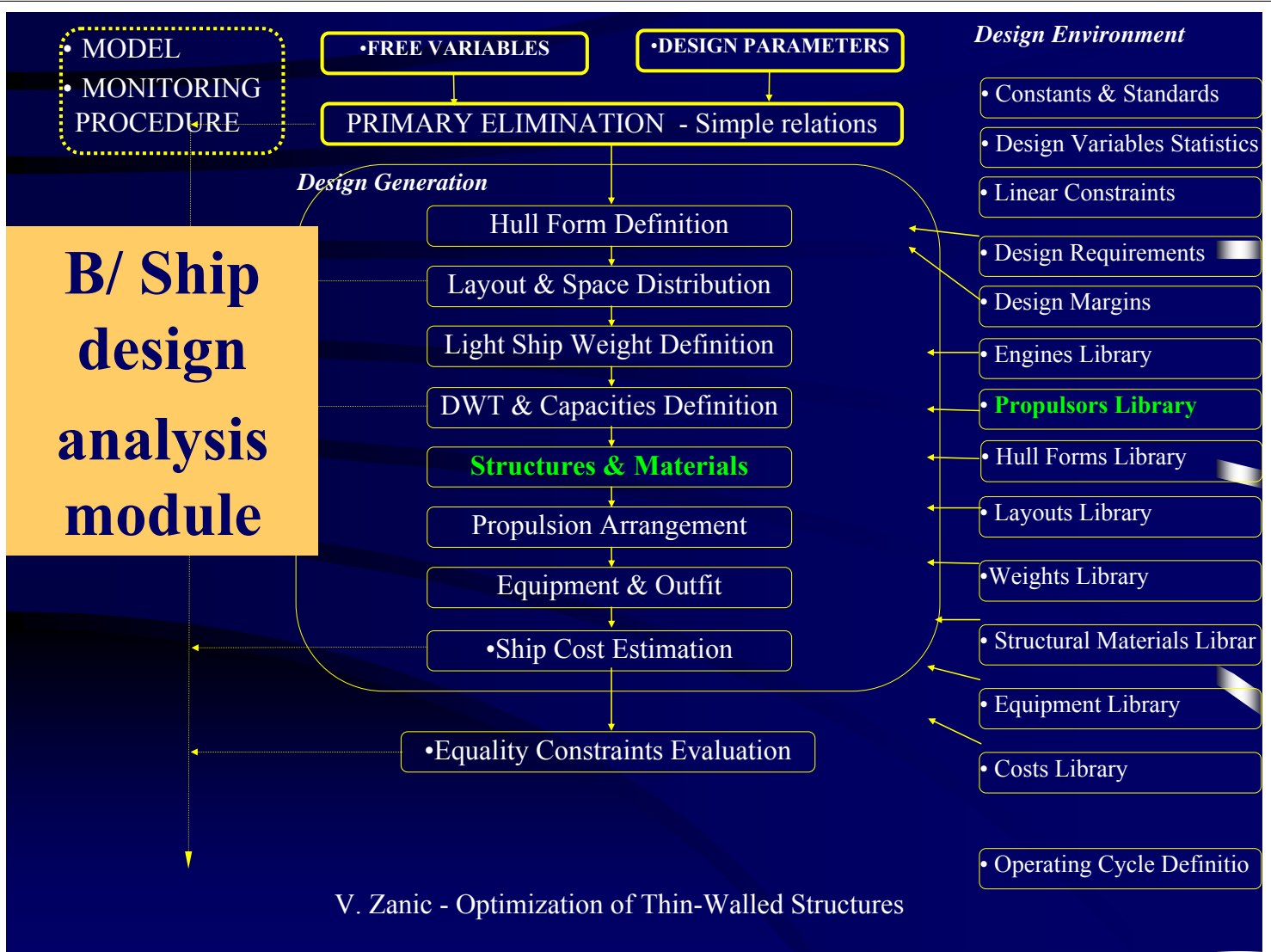
Automatic assesment of feasibility criteria for the selected strake using input from OCTOPUS solver

Calculates the feasibility criteria for the selected strake using user provided stresses and new scantlings

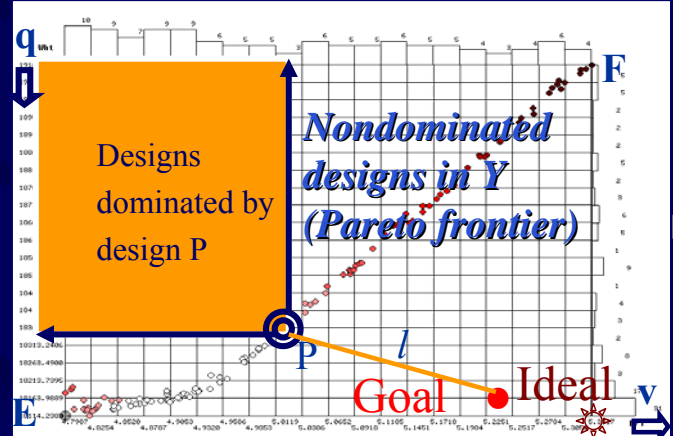
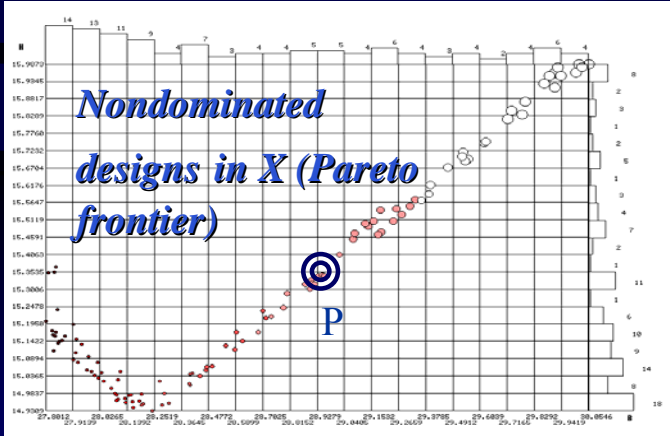
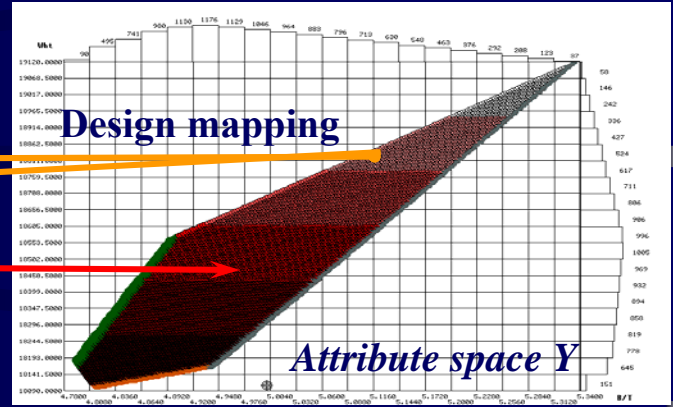
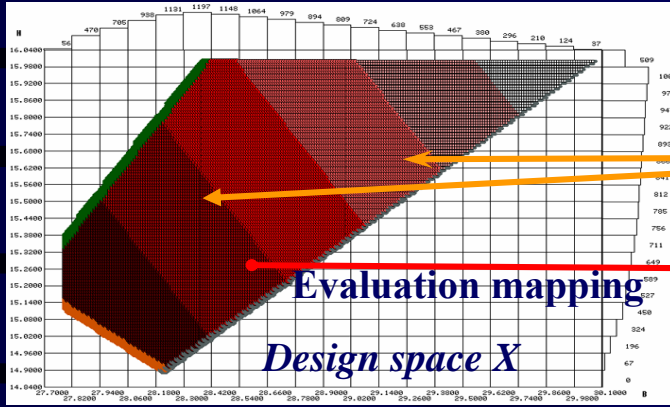
Independent safety criteria evaluation.



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2. DESIGN PROBLEM SOLUTION



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OCTOPUS - DECISION MAKING FRAMEWORK

DeMak - The Decision Making Framework - ROPAX - [Optimization_P0]

File Edit View Tools Windows Help

Model Jobs DeView

Job Selection: ID 1, Name: Optimization_P0, View, Sequence: View, Run

Subproblem: Opt. SubProblem 1, Model: ROPAX

Physical (Φ)	Environment	Response	Adequacy	Reliability	Quality
MM	LC1	PS	PSY	Beta-Unz.	Weight
mass	LC2	TS	PSB	B&Bou	Cost
	LC3	LS	PCY	Elem. FORM	Safety
			PCB		

Selected	Value	Min	Max	Step	Method
Dno.BSF	29,18	23	30	0,5	
Dno.HSW	157,7	125	162	1	
Dno.TPL	13	7,5	13,5	0,5	
Dno.TSF	22,3	13	22	0,5	
Dno.TSW	9	7,5	13,5	0,5	
UzvDna.TPL	11	8	13,5	0,5	
GirDna.HSW	150	130	170	1	
GirDna.TPL	12	10	15	0,5	
GirDna.TSW	12	7	15	0,5	
GP7.BSF	28,32	20	30	0,5	
GP7.HSW	142,4	120	160	1	

Analysis Methods Selection: Physic, Environment, Response, Adequacy, Reliability, Quality

Synthesis Methods Selection: Optimiser, Coordinatc, Visualizer

Subproblem List:

ID	Name	Variables	Parameters	Attributes	Constraints	Optimiser	NDOM
1	Opt. SubProblem 1	79		3	2496	ZV GASolver	

TestGenDat

Status

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SYNTHESYS MODULES

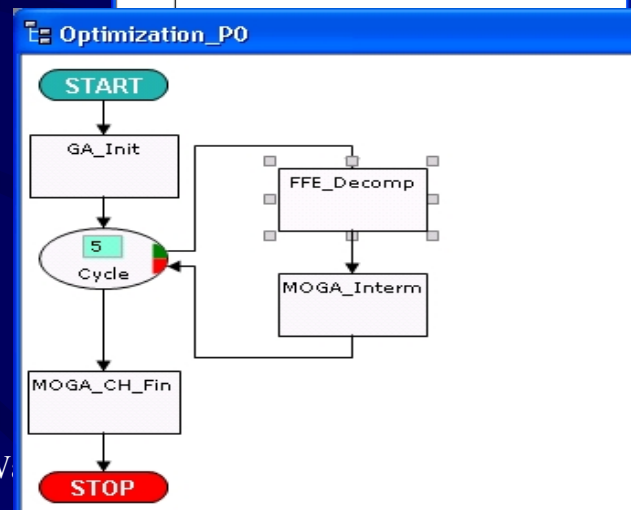
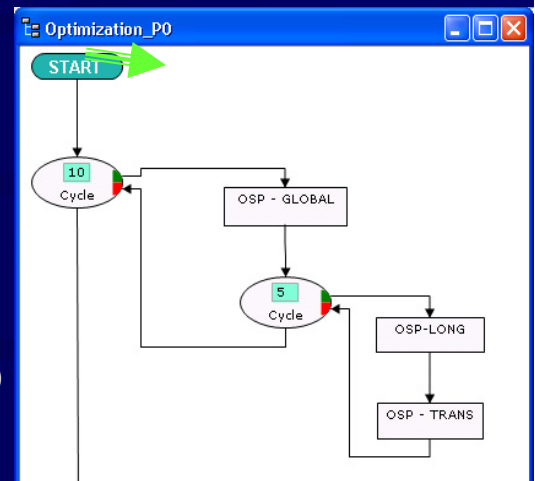
SYNTHESIS MODELS	OCTOPUS DESIGNER MODULES
Problem definition (Δ)	C# shell: SYNCHRO – decision support problem definition, selection of analysis and synthesis methods. Auxiliary modules: CAPLAN – control of Pareto surface generation LINC – definition of feasible subspace based on subset of linear/linearized constraints
Problem solution (Σ)	DeMak optimization solvers: MONTE – multilevel multi criteria evolution strategy FFE – Fractional Factorial Experiments CALMOP - SLP cross section optimizer MOGA - Multi objective GA DOMINO – Pareto frontier filter MINIS – subspace size controller HYBRID – combination solver-sequencer
Problem graphics and interactivity (Γ)	MAESTRO Graphic Environment De View C# Environment Design selection modules in metric space: GOAL - interactive goal input SAATY - inter-attribute preferences FUZZY - intra-attribute preferences COREL - statistical analysis of results

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PROBLEM DEFINITION (Δ) MODULES

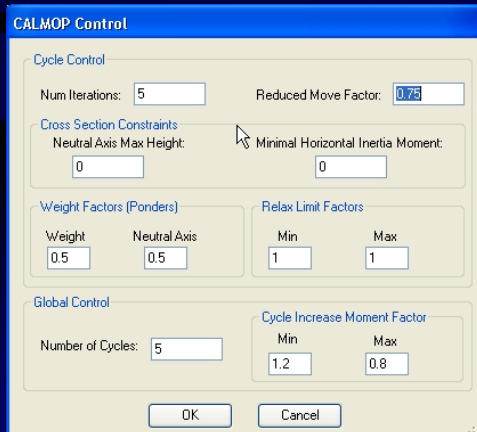
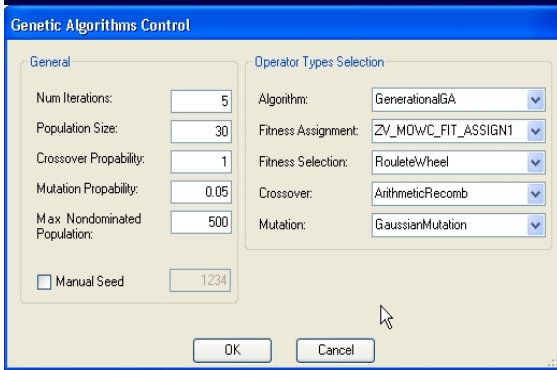
- Problem definition:**
 - **Objectives:** Minimal weight; Minimal cost; Maximal safety measures, etc. from (Ω)
 - **Variables** - subset of prob. descriptors (Φ, ϵ)
 - **Constraints:**
 - Minimal dimensions (Φ_{min})
 - Library of criteria from $(\alpha-1,2)$
- SYNCHRO** – decision support problem definition, selection of analysis (load, response, probabilistic data for $\epsilon, \rho-1,2,3$ and π) and synthesis methods, etc.
- AUXILIARY MODULES:**
 - **CAPLAN** – control of Pareto surface generation
 - **LINC** – definition of feasible subspace based on subset of linear/linearized constraints

Synchro
(Sequencer)



V. Zanic - Optimization of Thin-Walled Structures

PROBLEM SOLUTION (Σ): - Optimization solvers



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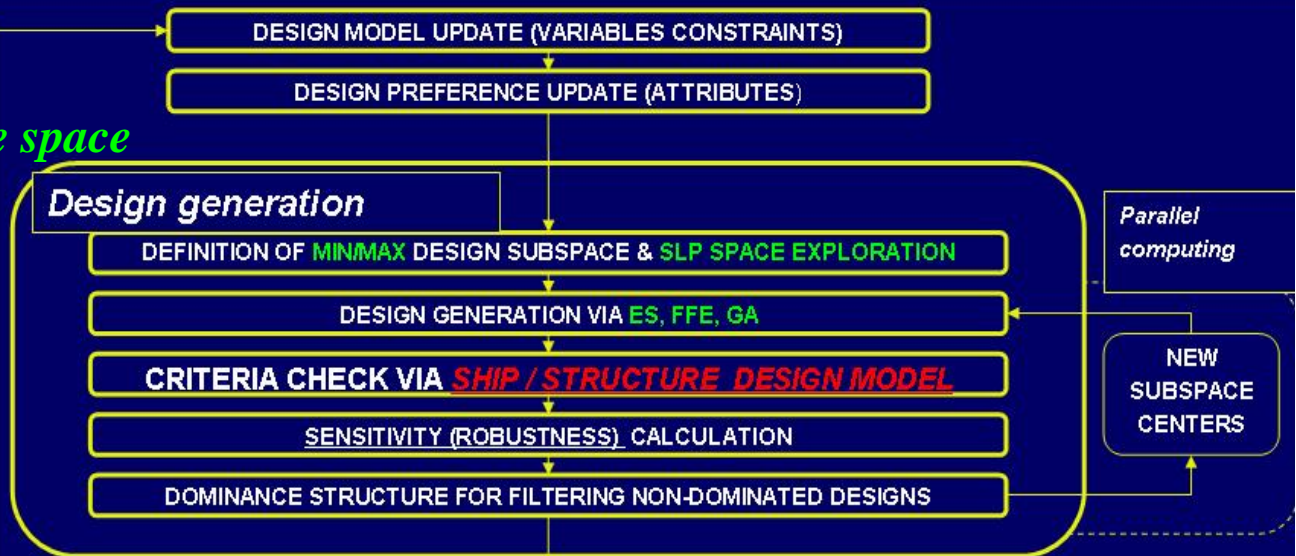
Optimization solvers :

- ❑ MONTE - multilevel multi criteria evolution strategies using :
 - Adaptive MC algorithm
 - FFE – Fractional Factorial Experiments
- ❑ CALMOP - SLP cross section optimizer
- ❑ MOGA - Multi objective GA
- ❑ HYBRID – combination solver-sequencer

Utilities :

- DOMINO – Pareto frontier filter
- MINIS – subspace size controller

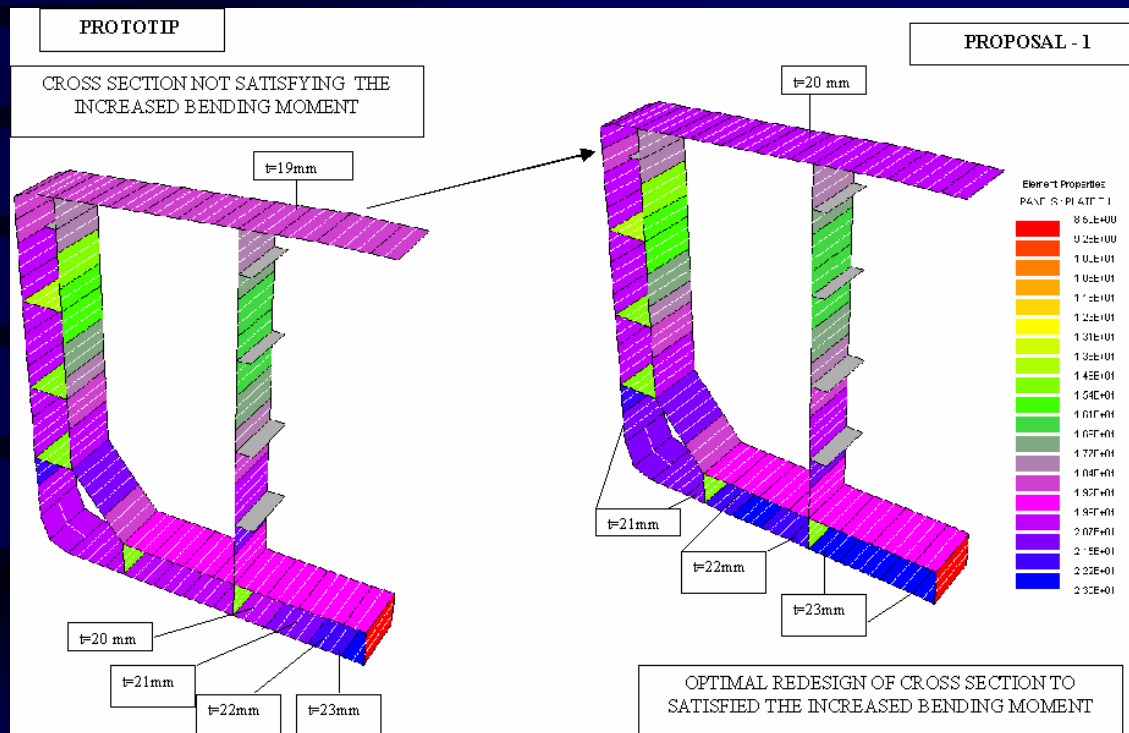
1. affine space



2. metric space

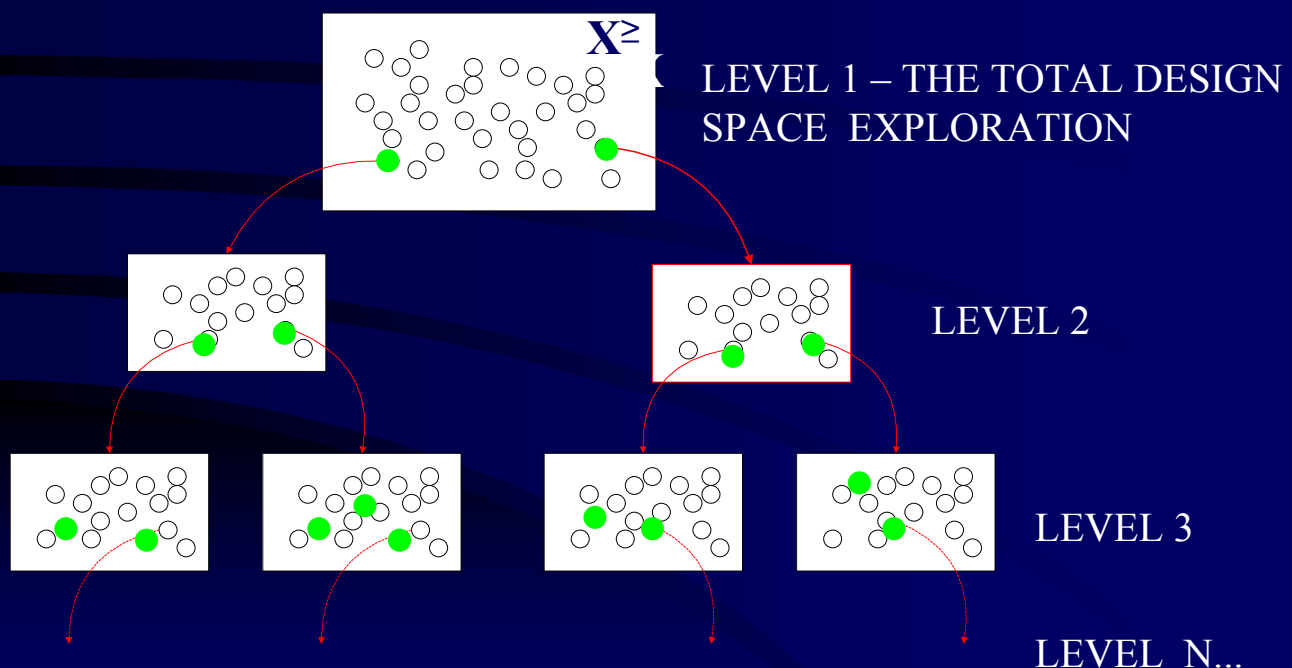


(1) CALMOP GLOBAL OPTIMISATION OF CROSS SECTION USING SLP



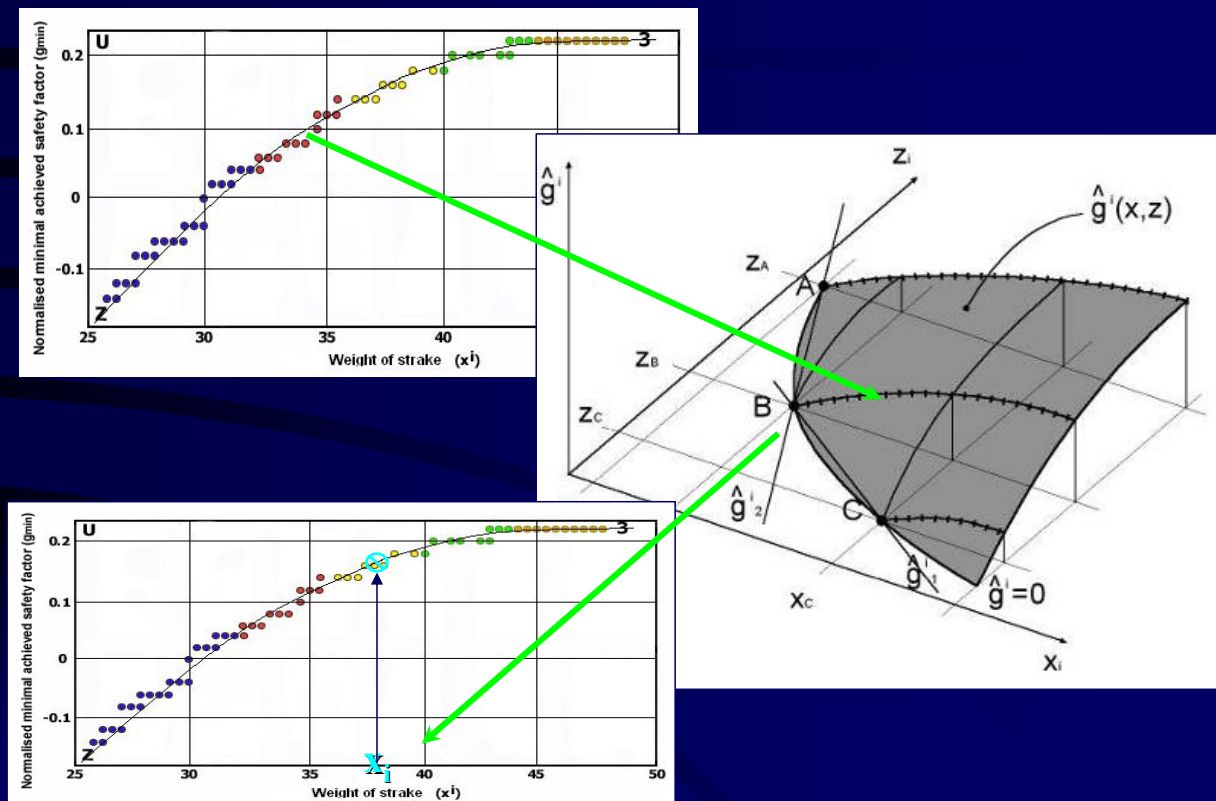
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(2) EVOLUTIONARY STRATEGY FOR SUBSYSTEMS (SUB-SYSTEMS e.g. GROSS PANELS)



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(1) + (2): GLOBAL – LOCAL COORDINATION USING ENVELOPE OF LOCAL FAILURE SURFACES

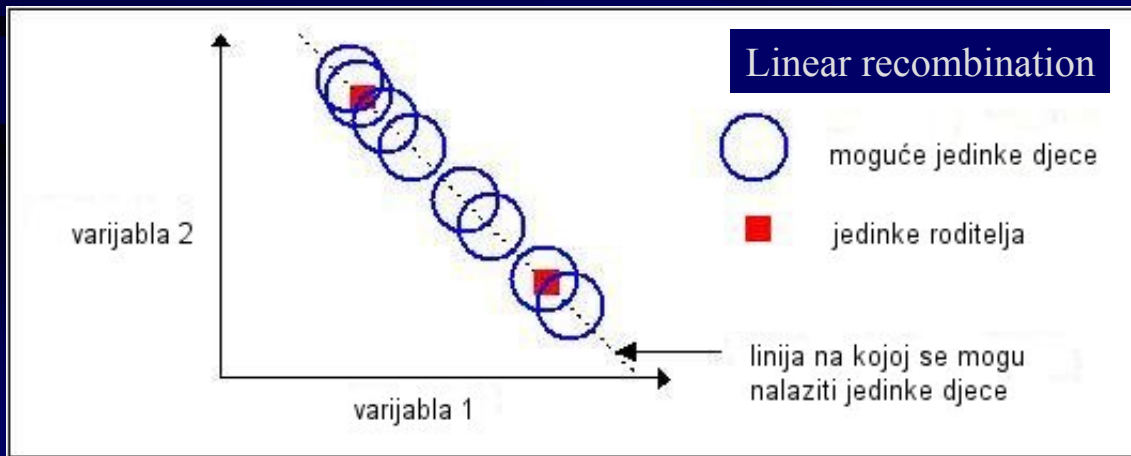
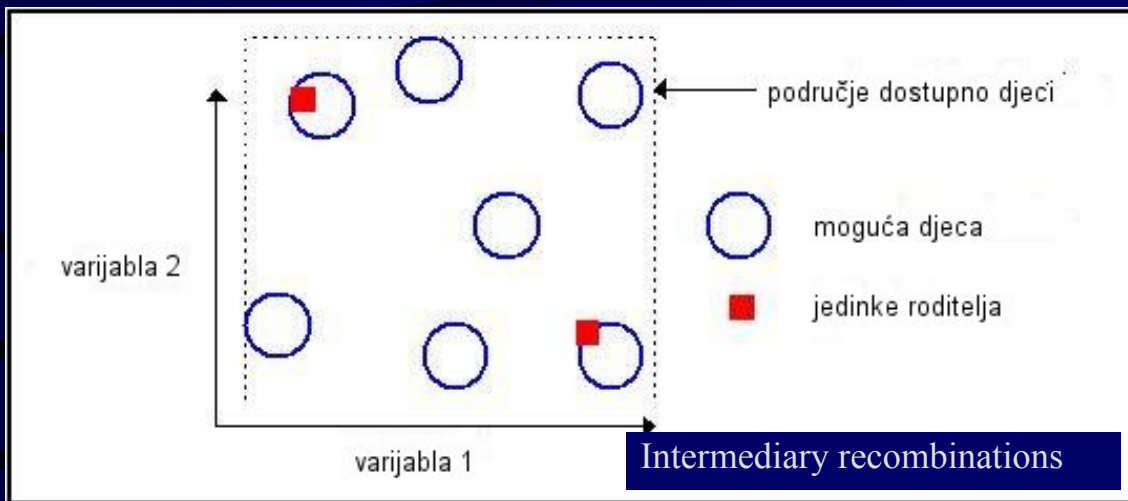


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(3) APPLICATION OF MOGA

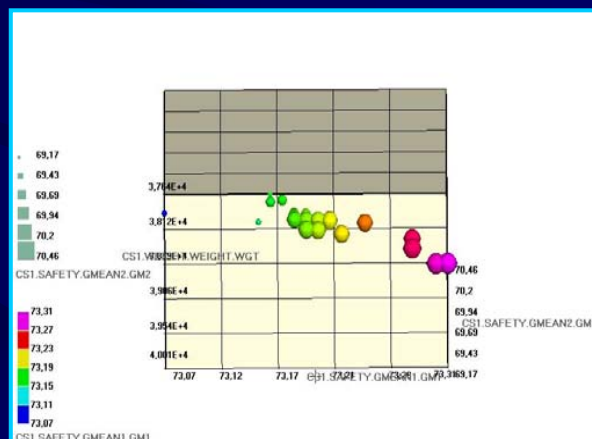
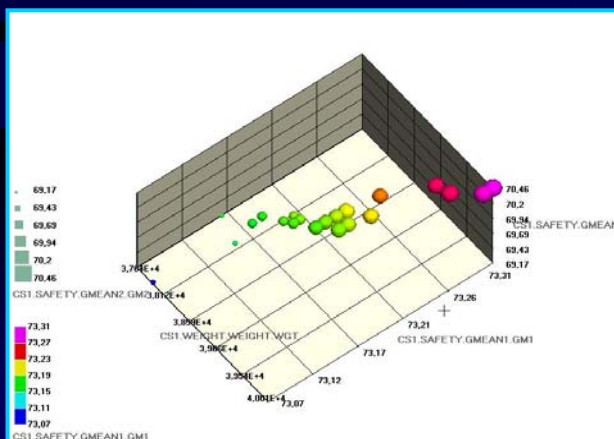
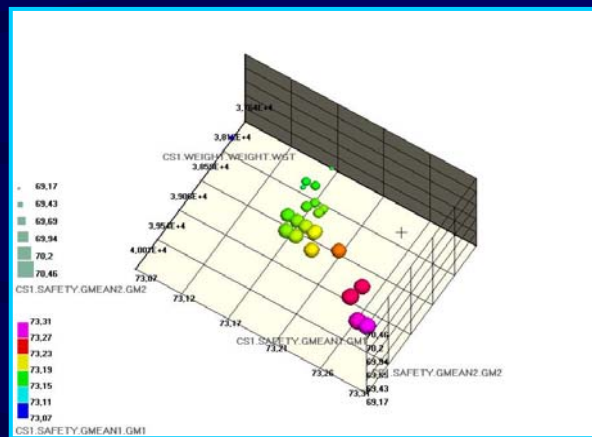
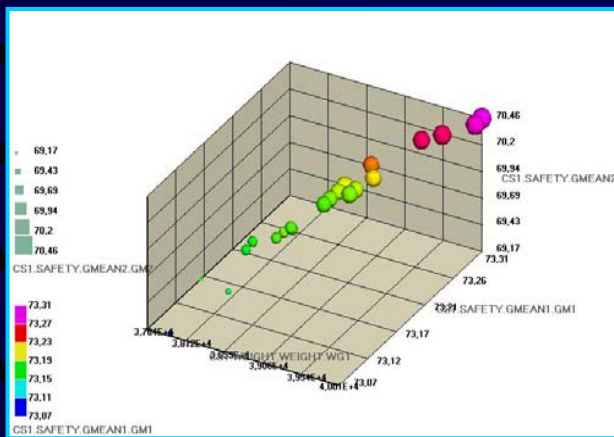
- Large problemS:
 - over 200 variables
 - more that 2.500 constraints
 - 3 objective functions
- Solved with standard generational and steady-state genetic algorithms
- Modification of fitness assignment operator was required
 - fitness value based on Pareto dominance
 - penalty for constraint violation
 - use of technique of fitness sharing for achieving better spread of Pareto front

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V. Zanic - Optimization of Thin-walled Structures

GRAPHICS MODULES (Γ): PARETO FRONTIER



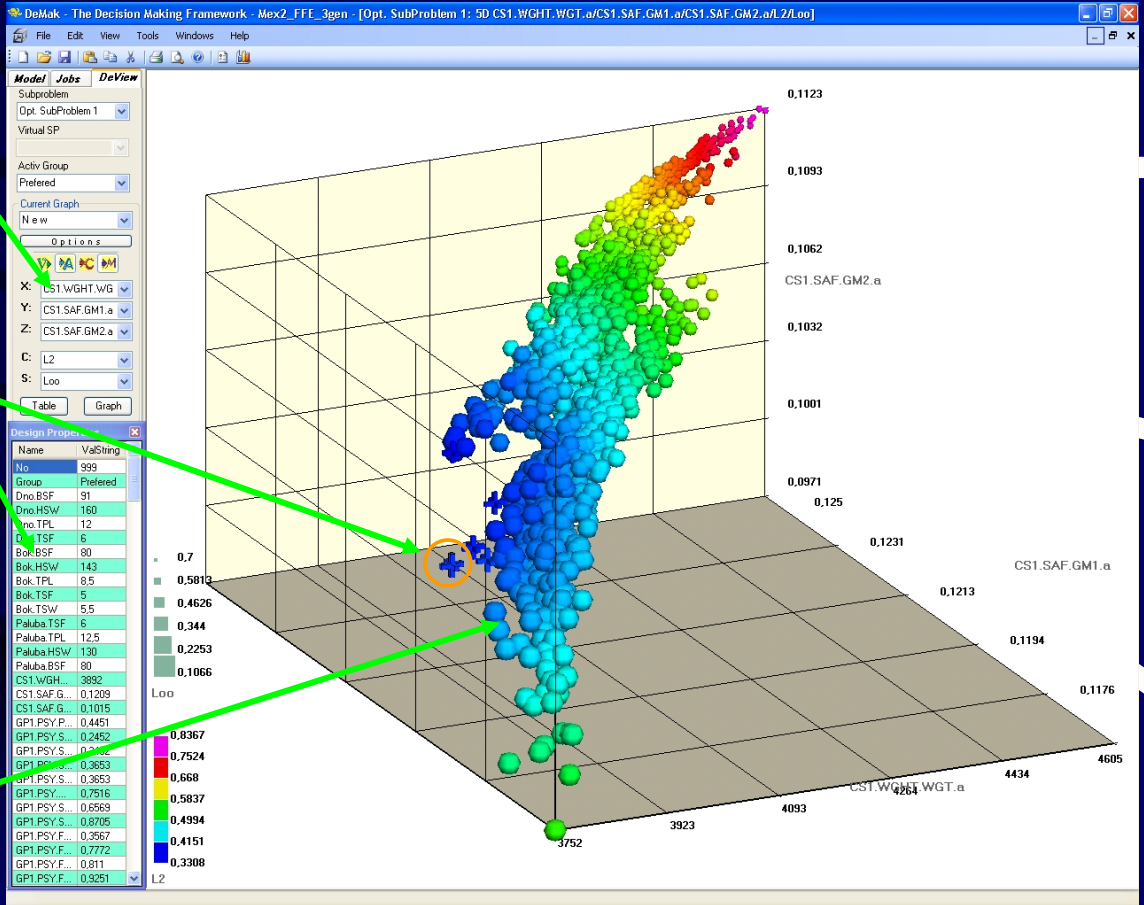
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DeView – PARETO SURFACE IN 5D SPACE

Visualization control for Graphs and Tables

Properties of the Currently Selected Design

Graphical Representation of Pareto surface



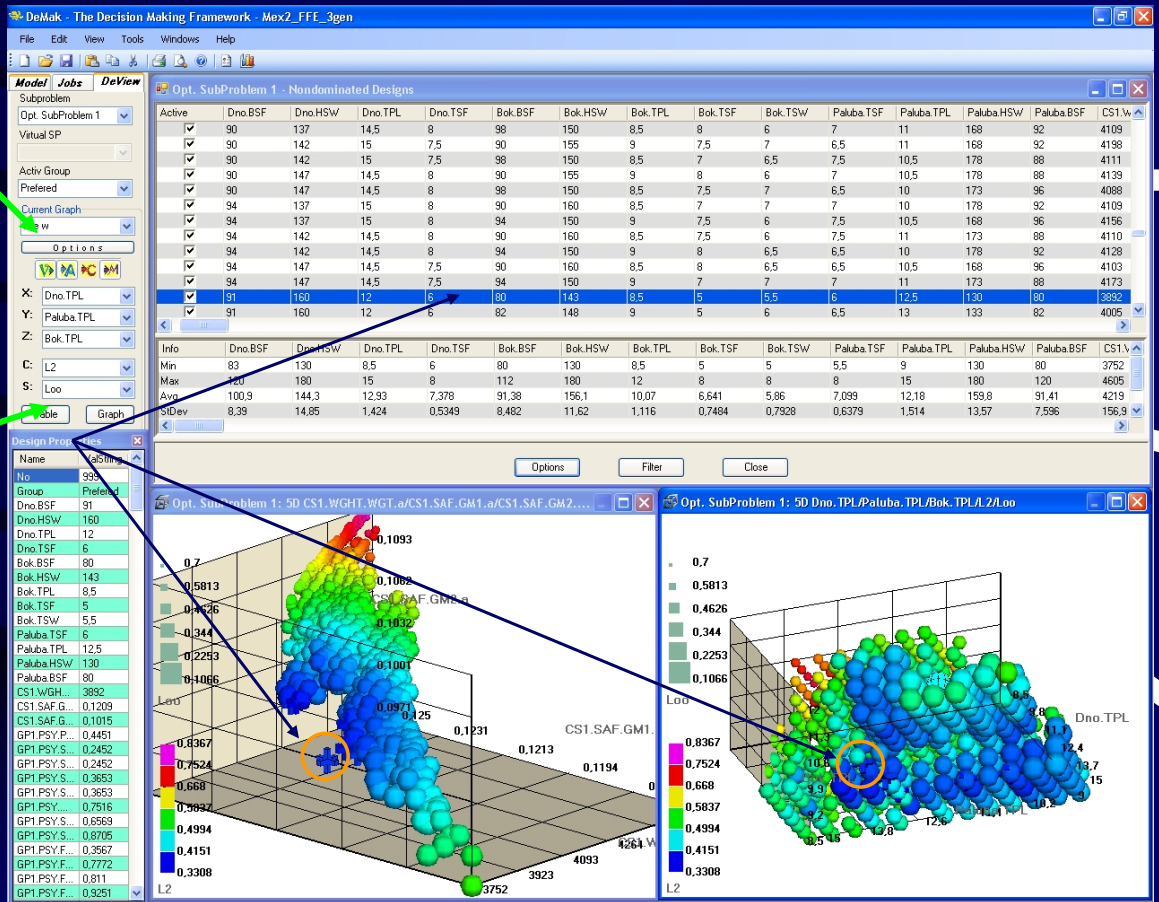
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DeView SNAPSHOT OF THE SELECTED DESIGN

Visualization control for Graphs and Tables

Properties of the Currently Selected Design (marked cross)

Multiple views of X+Y spaces (selection of the 5-axis views)



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DeMak – DEFINITION OF INTER / INTRA ATTRIBUTE PREFERENCES

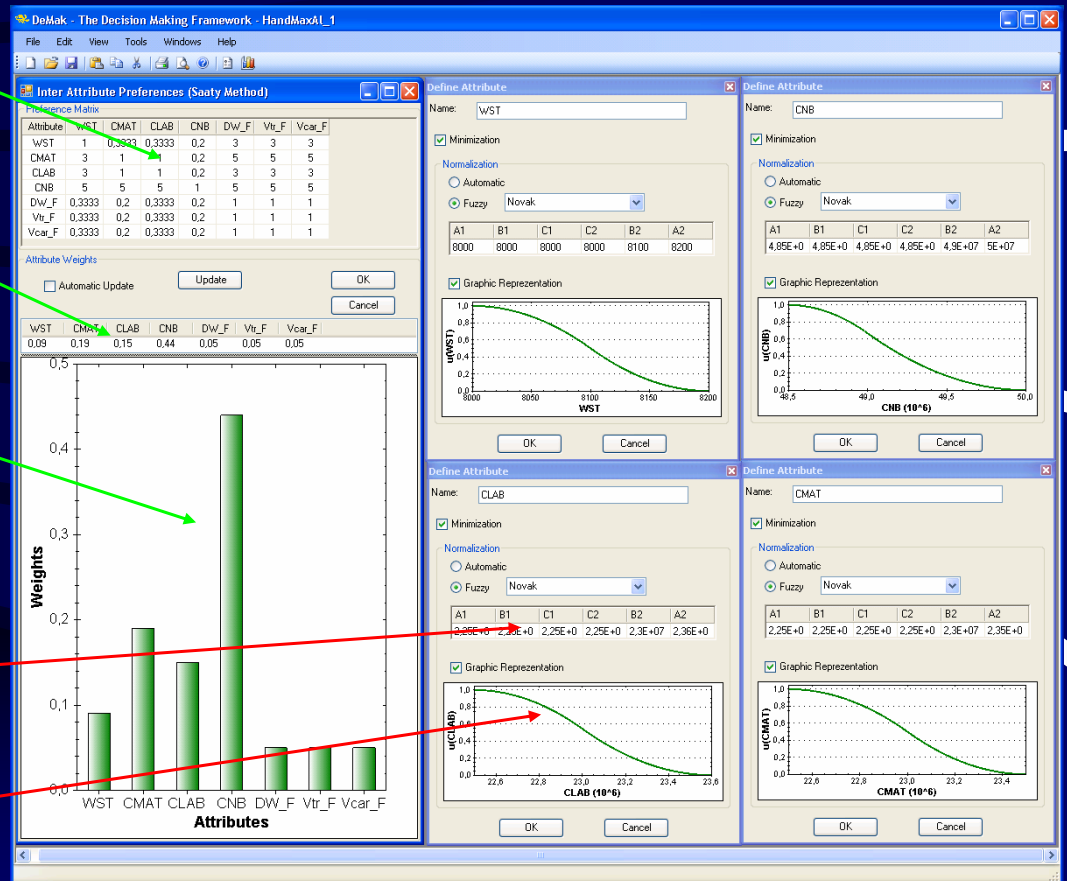
Inter Attribute Preference Matrix

Weights Calculated by Saaty Method

Weights Graphical Visualization

Fuzzy Functions Definition

Graphical Visualization of Fuzzy Functions



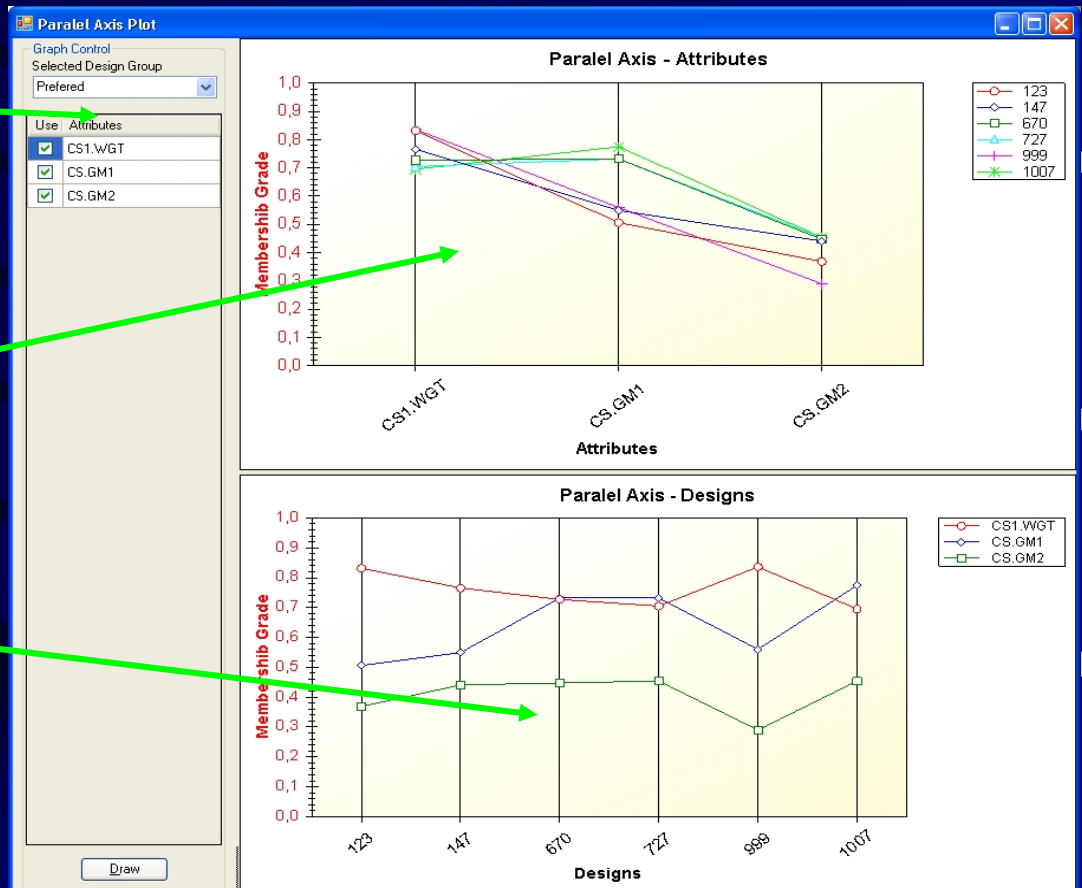
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DeView – PARALEL AXIS PLOT

Group and Attribute Selection

Attributes on X axis

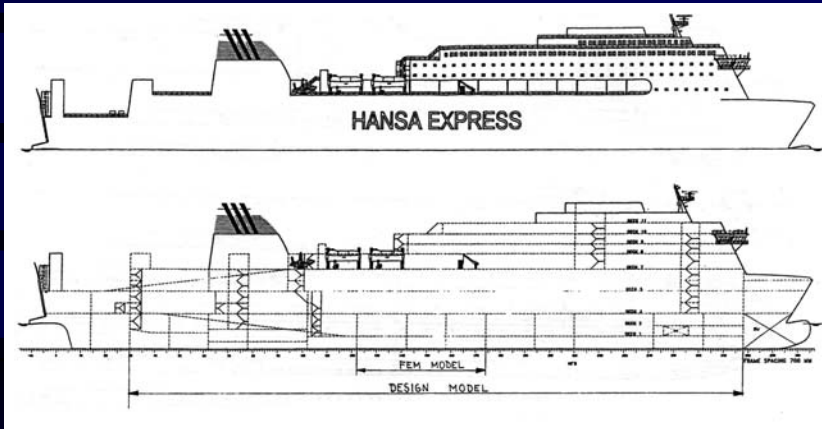
Designs on X axis



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3. APPLICATIONS

CASE STUDY A 1: Structural Design, Analysis and Optimization of Large RoPax (3500 lanemeters),



PRINCIPAL DIMENSIONS	
Length overall	221.2 m
Length between perpendiculars	207.0 m
Breadth max. o.f	29.0 m
Depth to bulkhead deck	9.8 m
Depth to deck 5	16.4 m
Design draft	7.0 m
Scantling draft	7.4 m
Lanemeters	3500 m
Speed at design draft with 4 engines at 85%	24.5 Kn

DeMak inbuilt into MAESTRO

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□ Design Problem Identification:

Design objectives $a_{1-3}(\cdot)$: min. weight, min. cost, max. safety

Free design variables $\underline{X} = \{\underline{x}^1, \dots, \underline{x}^{NS}\}$ are scantlings; $nv = 264$

Constraints $g(\underline{X}) \geq 0$; $ng \approx 49000$ from DnV Rules

Prototype P^0 scantlings from Yard documentation

Frame spacing and topology fixed to P^0 design values.

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PROTOTYPE: SAFETY ANALYSIS

Design sequence				
Step	Task	Method	Module*	
Prototype response analysis	1a	Rule load analysis	DNV	
	1b	Seakeeping load analysis	3D- panel	BV HydroStar
		Structural response and adequacy analysis	2.5-D FEM	LTOR-TOKV-EPAN
	2b	Primary ultimate strength analysis	Nonlinear analysis	LUSA+2a
	2c	Deterministic racking analysis	2-D FEM	TOKV-EPAN
	3a	Probabilistic a. of primary response	M_{sw}, M_{ult}	CALREL / SORM+2b
	3b	Probabilistic a. of racking response	β -unzipping	US3+2c
Concept design	4a	Reliability based concept optim.	OA (L27) designs	DEMAK / FFE+2b+3b
	4b	Filtering of Pareto prototypes	$P_{f-rack} - M_{mass} - M_{long-ult}$	DEMAK (DOMINO)
	4c	Selection of preferred designs	Value function	DEMAK-DEVIEW
	5	Deterministic optimization of preferred designs	Hybrid optimizer	DEMAK / SLP+FFE+2abc
	6	Reliability based re-optimization of optimal design	OA (L27) designs	DEMAK / FFE+3b
	Preliminary design	7a	Structural analysis and optimization	3-D FEM +SLP +DEMAK
7b		Probabilistic analysis of opt. design racking	β -unzipping	US3+2c
7c		Robustness analysis	Taguchi S/N Ratio	ROBUST

* see Table 1 and Figure 1.

Prototype deterministic safety analysis showed that **prototype failed in 35 criteria w.r.t DNV Rules (out of 8820 checks for 7 LCs) in:**

- double bottom (stiff. panels/ frames $g_{FCPB} = -0.268$)
- tank-side (st. panels e.g. $g_{U-BCAES,min} = -0.172$)
- deck5-middle (st. panel e.g. $g_{PFLB,min} = -0.243$)

Ultimate bending moment-LC1(sagg)=3.93 106 kNm
LC2 (hogg)=3.18 106 kNm (bottom collapse in compression-see above).

Identified failed elements were non-optimally strengthened (mass increased 1.2%; strong prototype ■)

System failure probability (Ditlevsen upper bound) for the 45 identified relevant (level-3) failure scenarios was: $p_f = 0.101 \cdot 10^{-6}$; $\beta_G = 5.198$ showing the existence of **considerable safety margin**

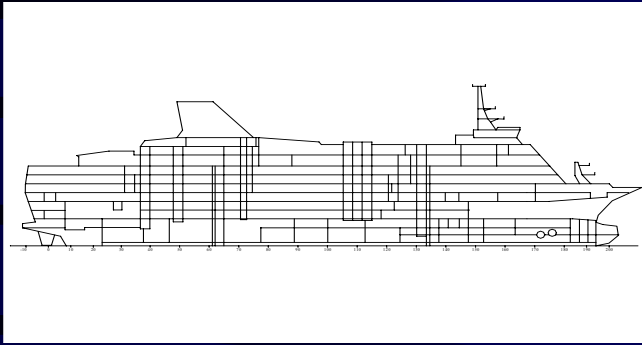
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Optimization results

MODEL	Geometry S_w L_{FEM} (mm)	Weight of optimization model (t)		Weight per length W_{opt} / L_{FEM} (t / m)	Savings before final standard. $(\frac{W_{start} - W_{opt}}{W_{start}})$	Global safety (adequacy) measure	Weight of design model $W=L*k*w_L$ (t)	Increased deadweight = decreased steel weight
		W_{start}	W_{opt}					
PROTOTYPE	2800	1355	40.33	-	0.9622	5646	-	
	33600	-	-	-	-	-	-	
PROPOSAL 1	2800	1355	36.31	9.97%	0.9905	5083	563 t	
	33600	1220	-	-	-	-	-	
PROPOSAL 2	2400	1202	36.32	9.94%	0.9889	5085	561 t	
	28800	1046	-	-	-	-	-	
PROPOSAL 3	3000	1416	35.61	(11.70 %)	0.9719	4985	661 t	
	36000	1282	-	-	-	-	-	
PROPOSAL 4	2800	1382	33.90	experiment	0.9683	/	/	
	33600	1139	-	-	-	-	-	

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CASE STUDY 2: Structural Design, Analysis and Optimization of Passenger/Car Ferry (L=169 m, 11 decks)



MAIN PARTICULARS:

LOA = 176,0 m

LPP = 169,0 m

B = 32,0 m

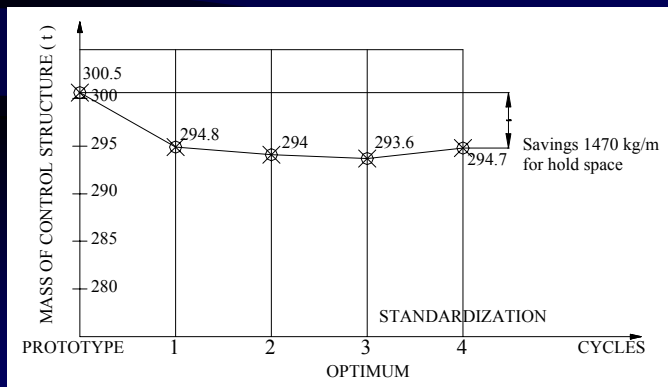
T = 10,0 m

Speed trial = 22 Kn

2200 passengers

600 cars

OPTIMIZATION PROCEDURE



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The four ships of this type have been **built in Croatia** and they **operate in the Baltic**.

The optimization was performed due to the owner's conflicting **requirements on ship weight and vibration criteria**.

Cost sensitivity study with respect to frame spacing (800, 850 and 900 mm) was performed for the third and fourth ship.

Design process is divided into two parts :

optimization for weight critical design

cost sensitivity study with respect to frame spacing.

The **optimization model** included : 492 scantlings of design variables

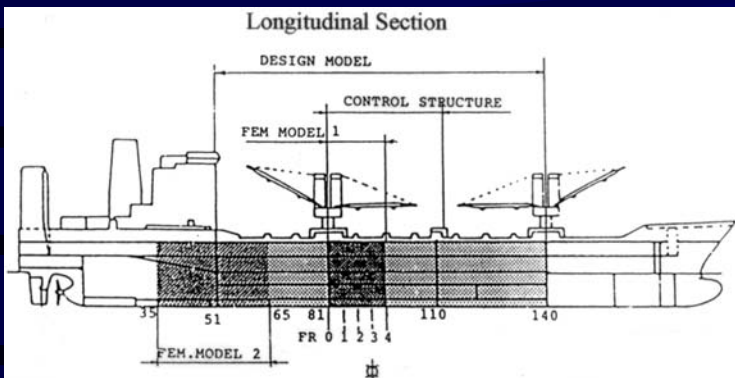
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Results

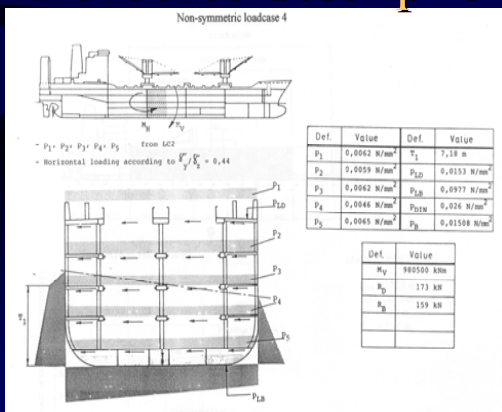
- Problem of structural adequacy is solved by **simultaneously resolving 49 unsatisfied failure** criteria of the very sophisticated prototype.
- Weight decrease of 600 kg/m has been achieved for critical weight constrained design, as compared to the minimal weight prototype, giving **60 tons of weight reserve** to the designer to be used in satisfying vibration criteria.
- Sensitivity study shows that the cost of structure per meter is rather **insensitive to frame spacing**, in given interval, due to cancellation of the effects of structural modifications and smaller number of web frames.

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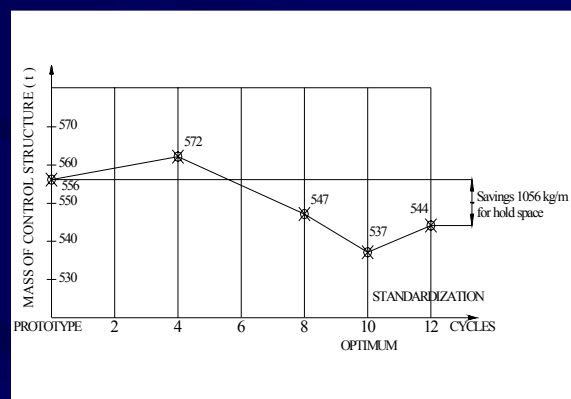
CASE STUDY 3: Structural Design, Analysis and Optimization of **Reefer/Ro-Ro Ship (47000 cbft)**



Loadcase description

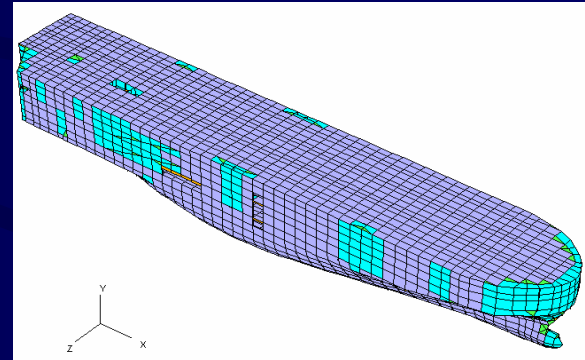


Optimization Procedure



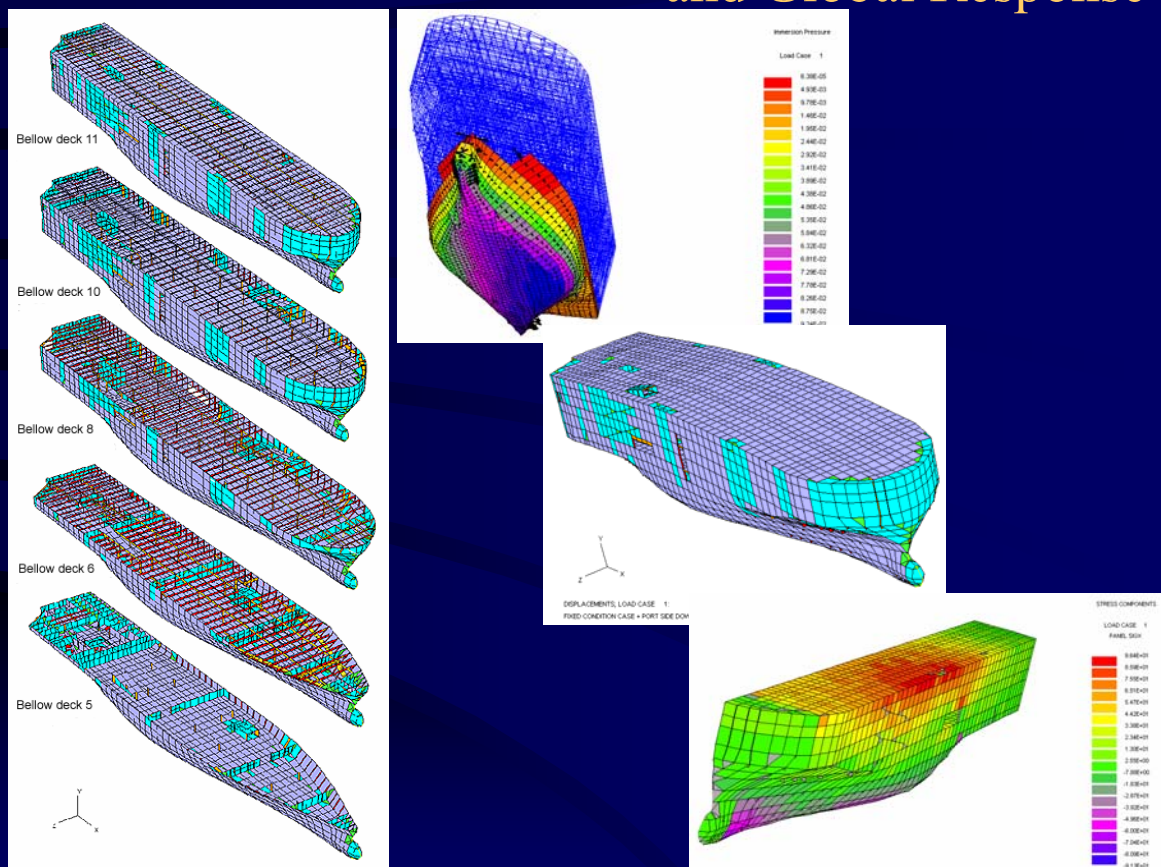
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CASE STUDY 4: Structural Design, Analysis and redesign of **Car-Truck Carrier** LOA = 176.7 m, 5300 cars



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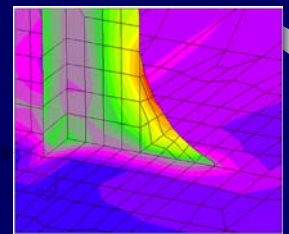
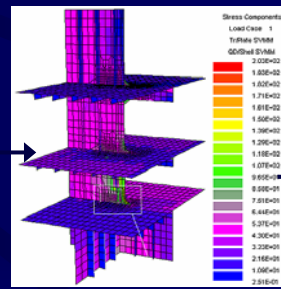
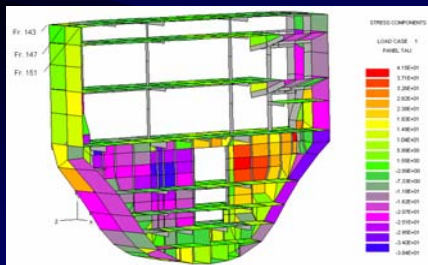
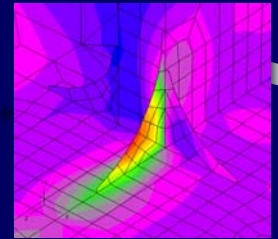
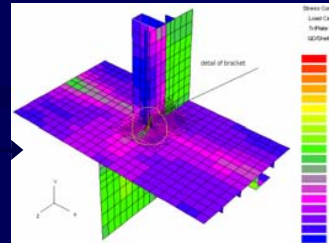
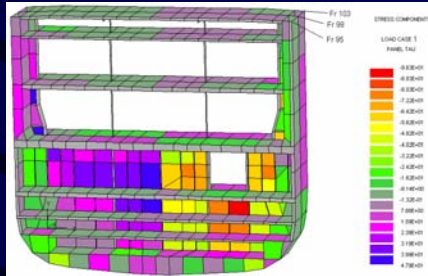
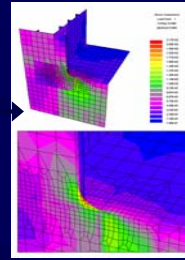
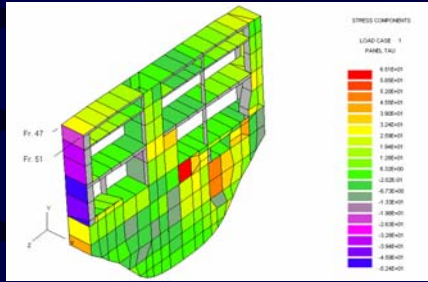
Full Ship F.E.M Model, Immersion Load and Global Response



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Global Respons

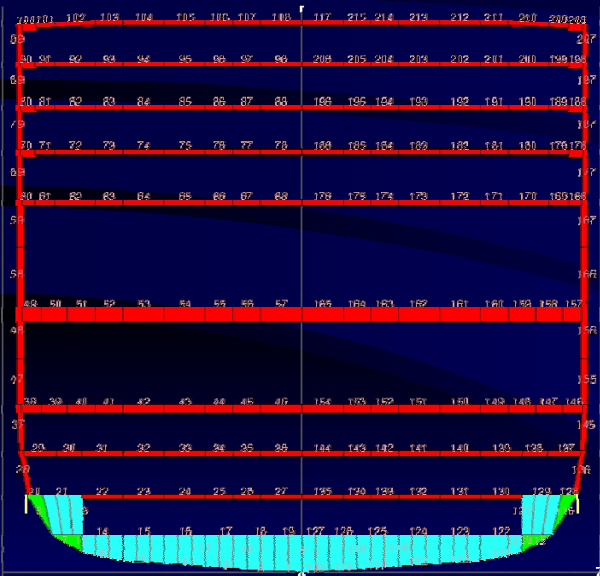
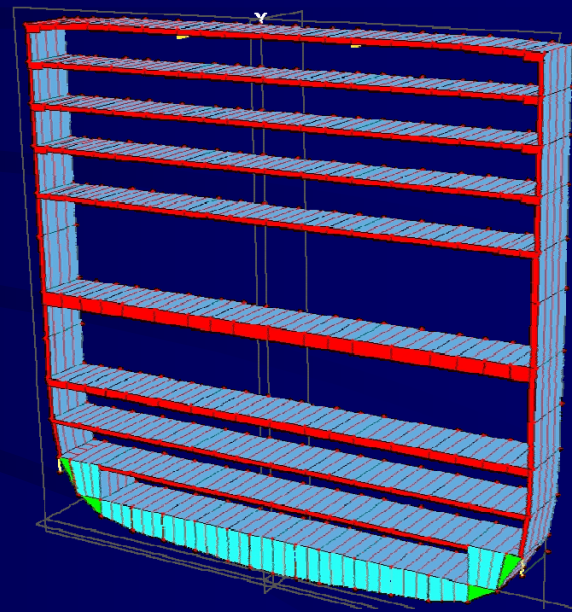
von Mises Stresses for Fine Mesh Models



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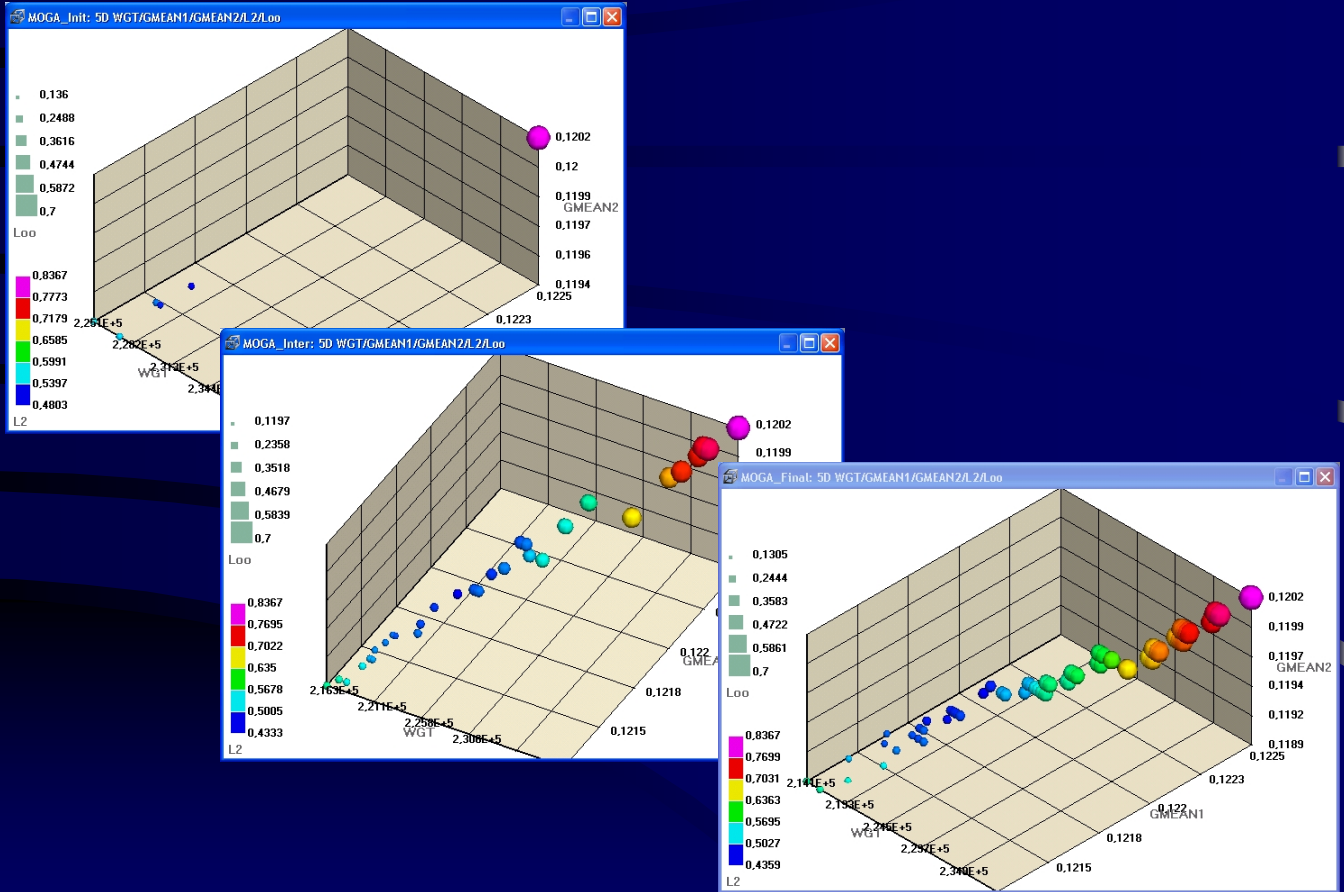
MOGA optimisation of CAR CARRIER

	Number
Design Variables:	635
Constraints:	2469
Objectives:	3



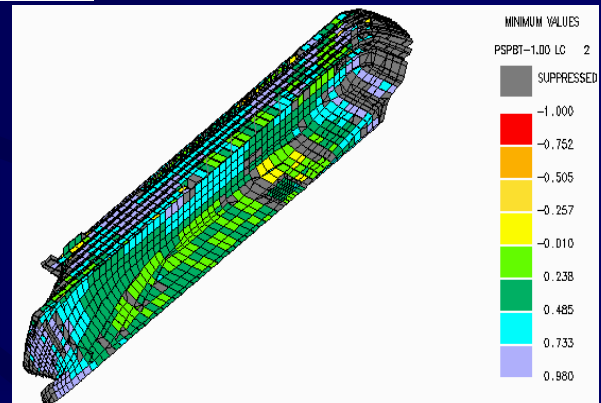
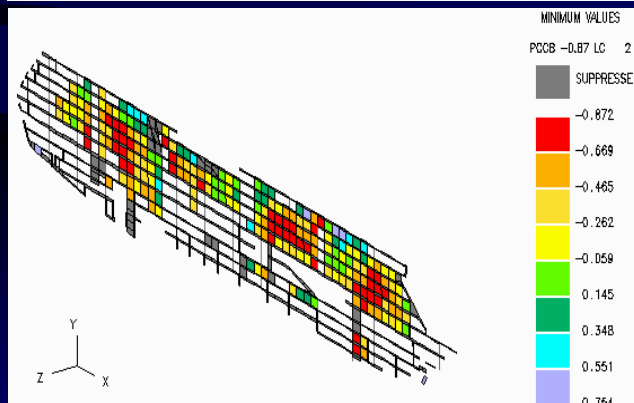
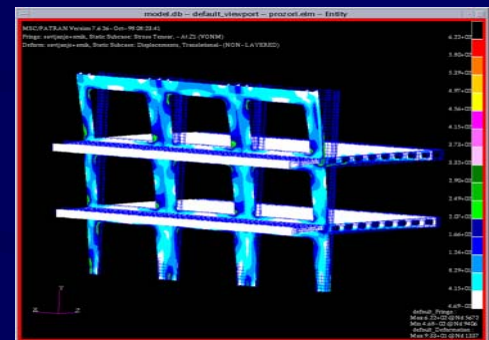
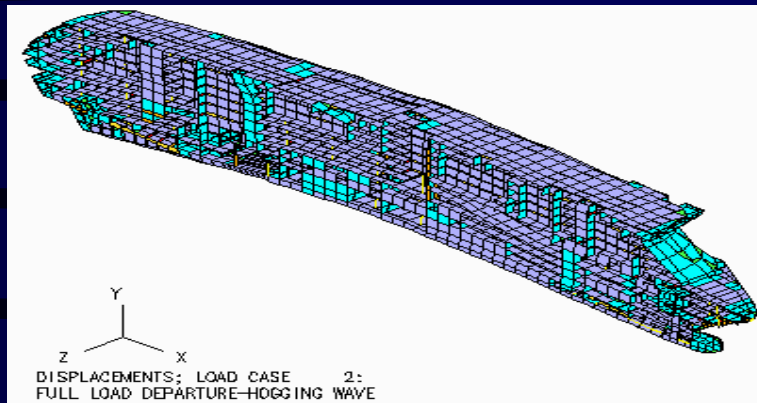
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PROGRESS OF PARETO FRONTIER



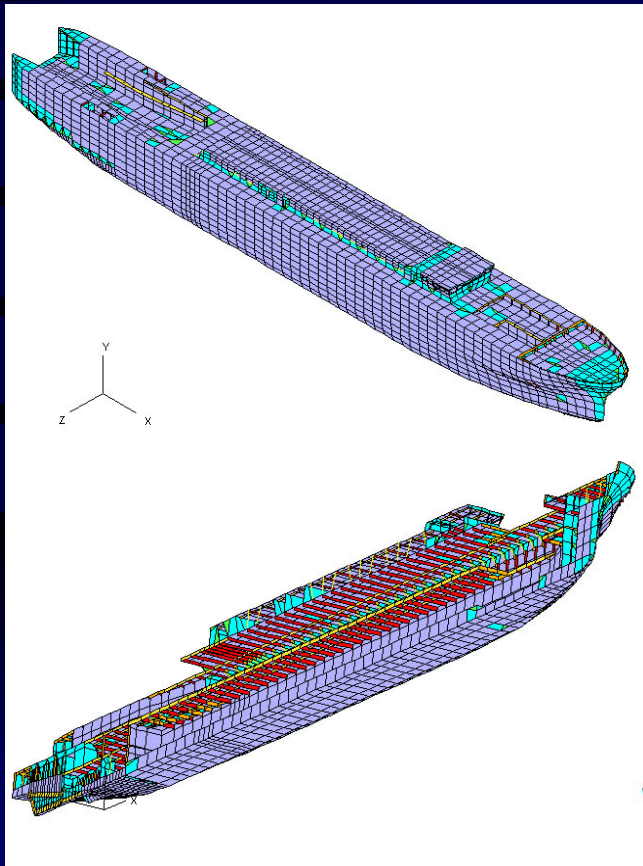
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CASE STUDY 5: First class passenger ship (800 passengers) Redesign for Cantieri Nuovi di Apuania, Navis Consult-Rijeka



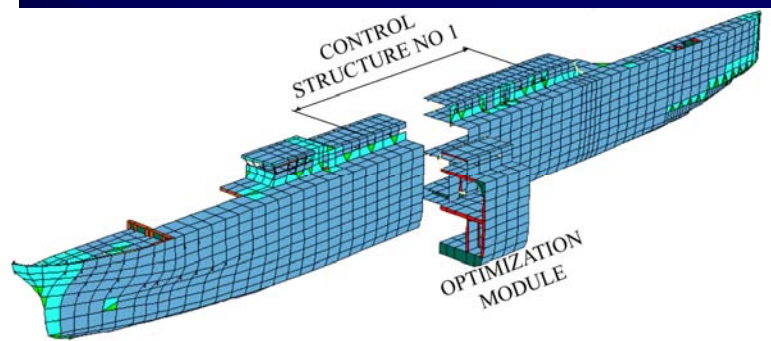
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CASE STUDY 6: Structural Design, Analysis and Optimization of Tank car carrier (L=52 tank cars)

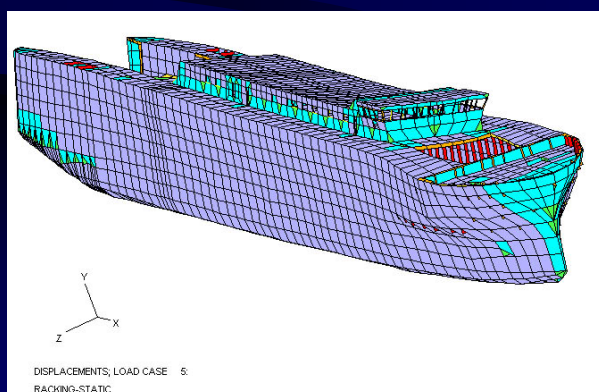
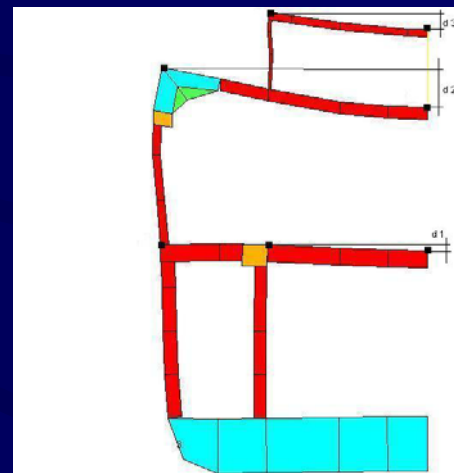
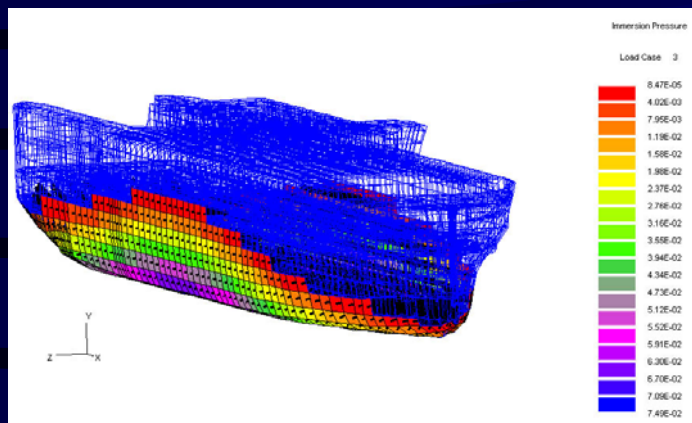


Principal dimensions:

Length overall	154.50 m
Length between perpendiculars	147.00 m
Breadth moulded	17.50 m
Breadth max.	18.30 m
Depth to upper deck	7.50 m
Depth to accommodation deck	13.35 m
Draught	7.70 m
Deadweight	5000 t
Main engines	2 X 2000 kW
Speed trial (80% MCR)	14.0 knots
Wagons	52

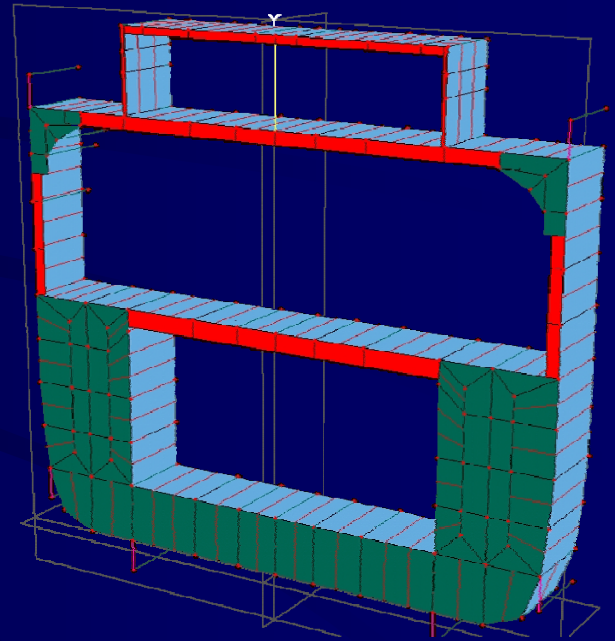
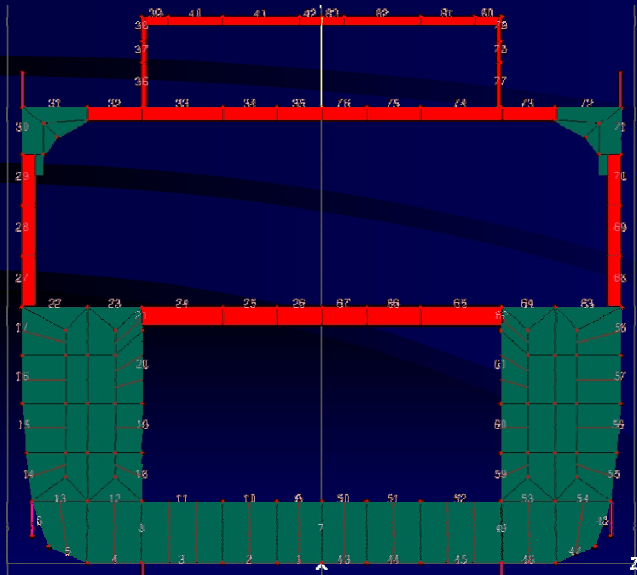


Loads and Response



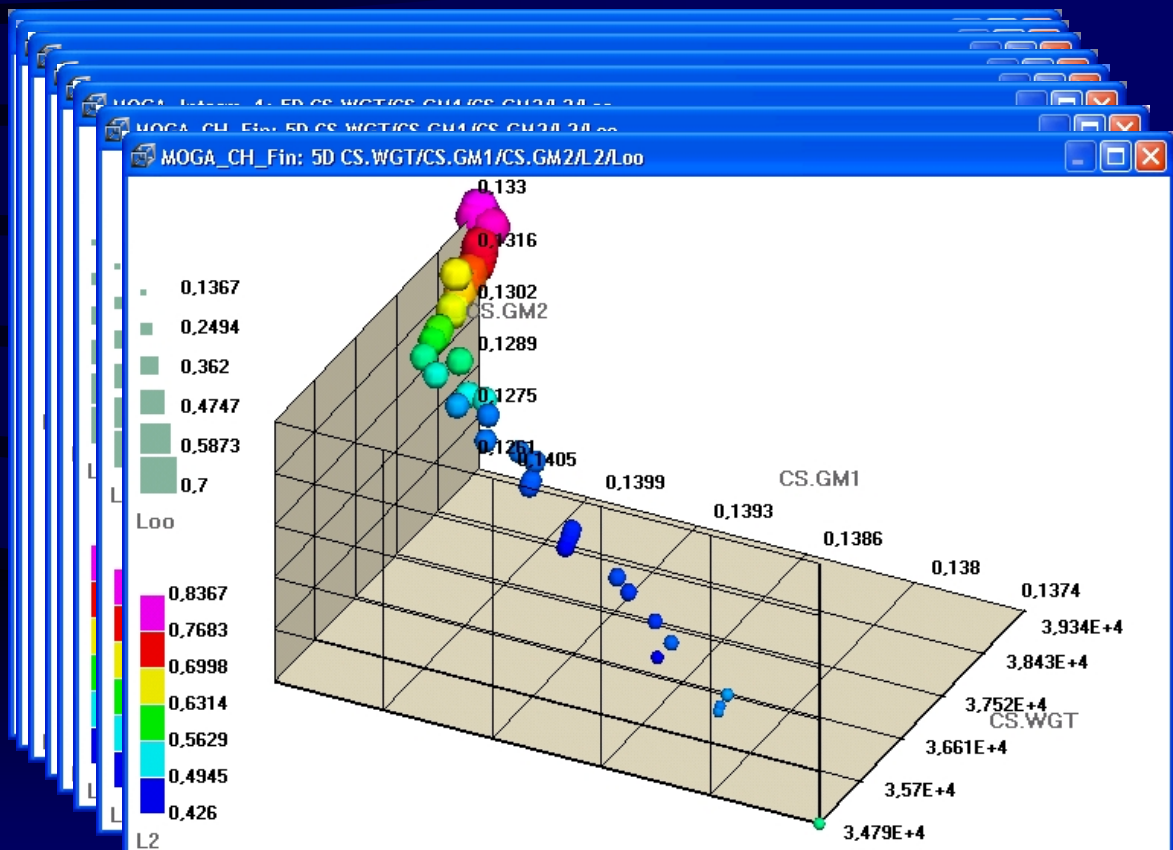
CONCEPT STRUCTURAL DESIGN OF THE TANK CAR CARRIER (MOGA)

	Number
Design Variables:	79
Constraints:	2496
Objectives:	3



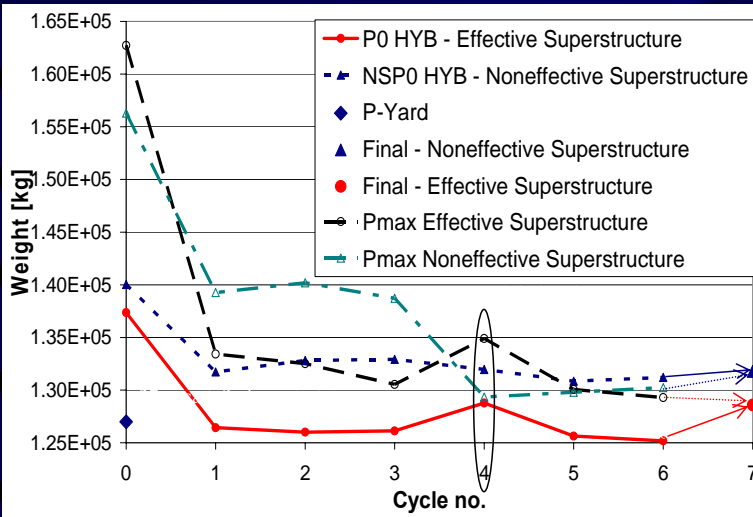
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PROGRES OF PARETO FRONTIER

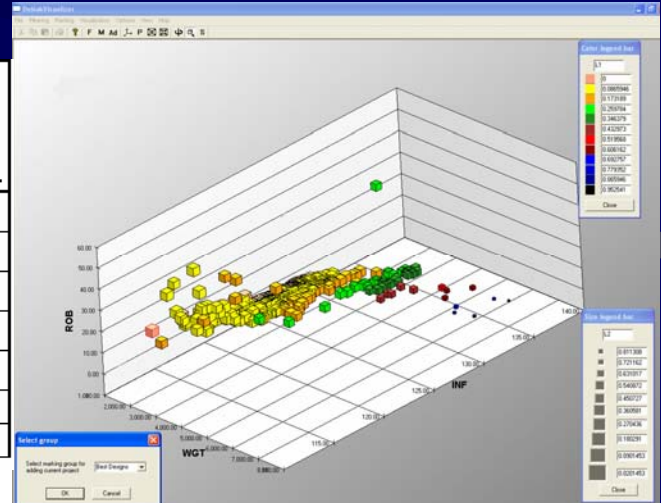


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PRELIMINARY STRUCTURAL DESIGN OF THE TANK CAR CARRIER (DeMak Hybrid solver incorporated in MAESTRO)



Model	Mass Opt. Module (t)	Mass Control Structure (t)	Unsatisfied Criteria		Weight Savings W.R.T. P0	Weight Diff. W.R.T. Final D.
			num	Min.val.		
P^{ms}	127.1	699.05	-37	-0.25	/	
Effective SS	P_1^0	136.4	750.2	0	/	
	O_1^2	125.2	688.6	-5	-0.08	8.2%
	D_1^2	128.6	707.3	0	/	5.7%
Noneffective SS	P_2^0	141.6	778.8	0	/	
	O_2^2	131.2	721.6	-3	-0.05	7.3%
	D_2^2	131.7	724.3	0	/	7.0%

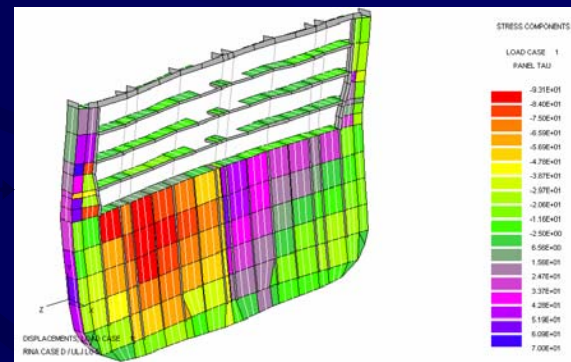
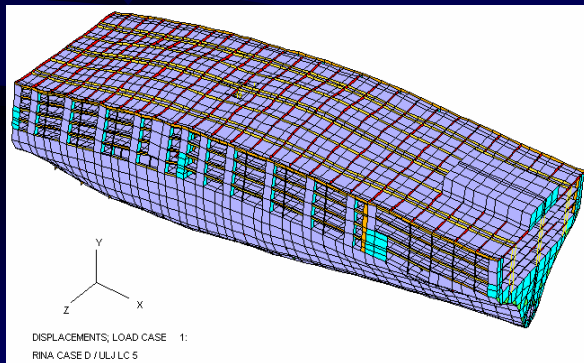
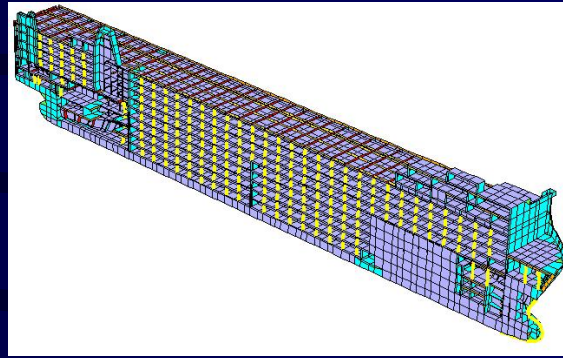


CASE STUDY 7: Livestock Carrier (LOA = 176.7 m, 24 000 sq.meters) Yard no. 428 for ULJANIK Shipyard.

Objective of case study was to demonstrate:

- The structural analysis and redesign of the FEM model of livestock carrier according to R.I.N.A Rules.
- Racking analysis to identify relevant critical areas in the transverse structure.
- Detail design : Feasibility of additional openings in principal structural members through the fine mesh models

Longitudinal Section and Global Respons



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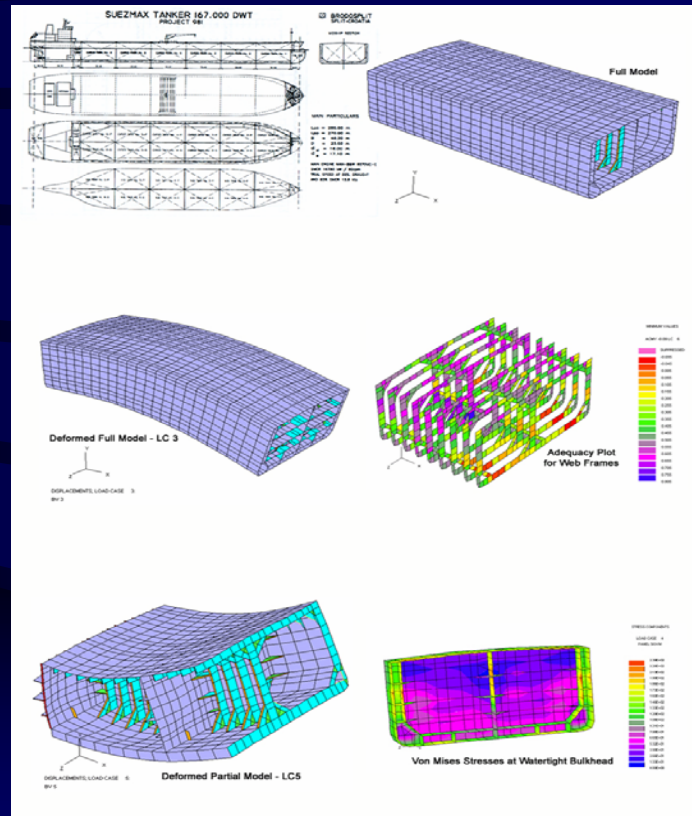
CASE STUDY 8A: Suezmax Tanker (LOA = 280.0 m, 166 300 TDW) Yard no. 433-434, for BRODOSPLIT Shipyard.

Objective of case study was to demonstrate:

- The optimization process for 3 prototypes of SUEZMAX tanker with web frame spacing of 3940, 4410 and 5065 mm.
- Structural optimization for minimal structural weight under class.soc. requirements.
- Sensitivity analysis of ship structural weight with respect to web frame spacing.
- Fine mesh stress analysis (DSA) of final PROTOTYPE under BV requirements as decision support problem for final scantlings determination.

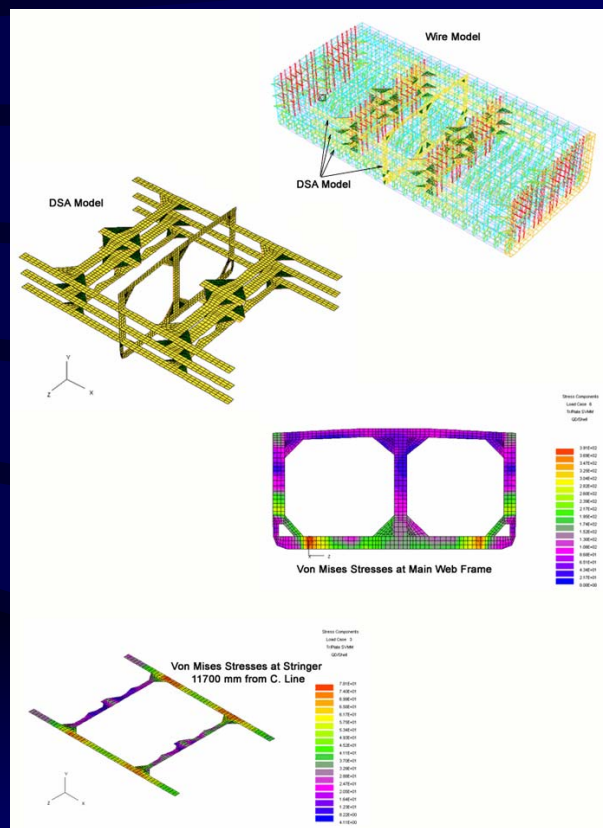
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Longitudinal Section, F.E.M Model and Global Respons



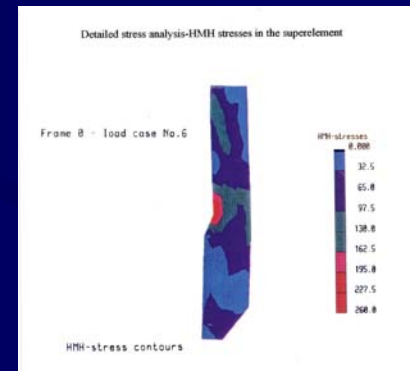
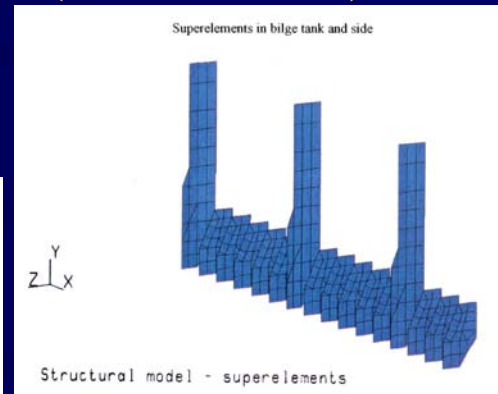
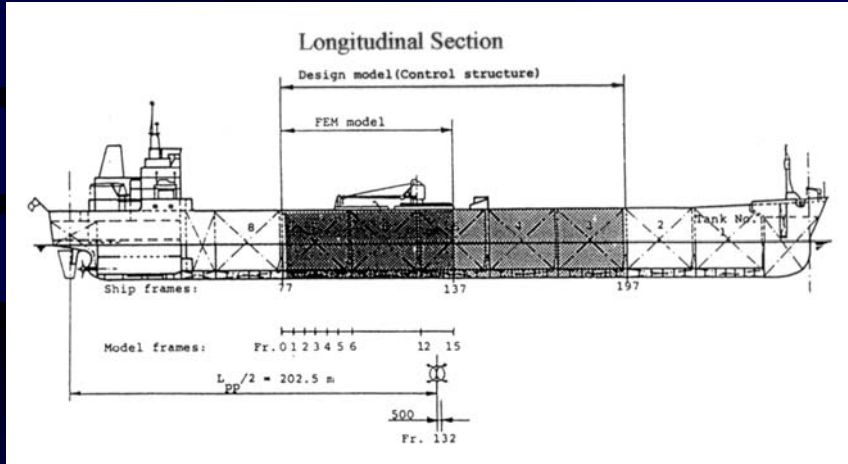
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DSA/Fine Mesh Model – Maximum Principle Stresses



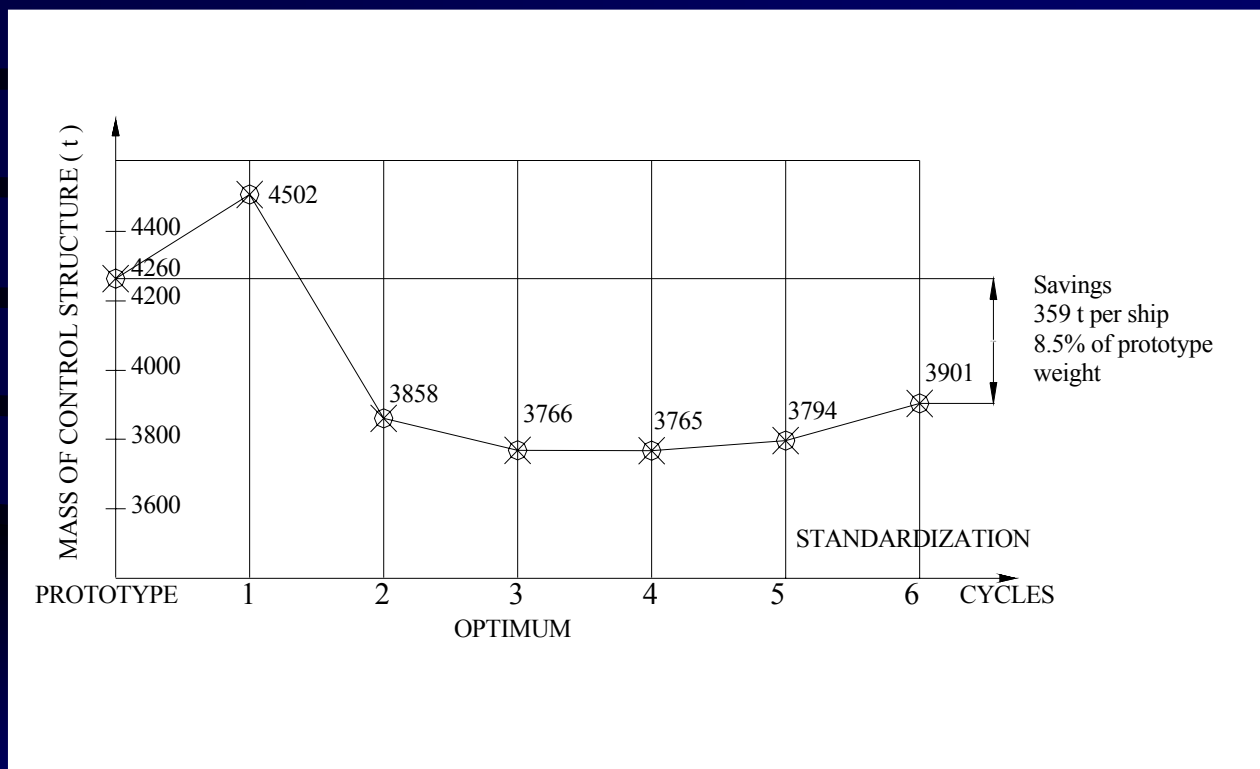
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CASE STUDY 8B: Structural Design, Analysis and Optimization of Tanker for oil (70000 TDW)



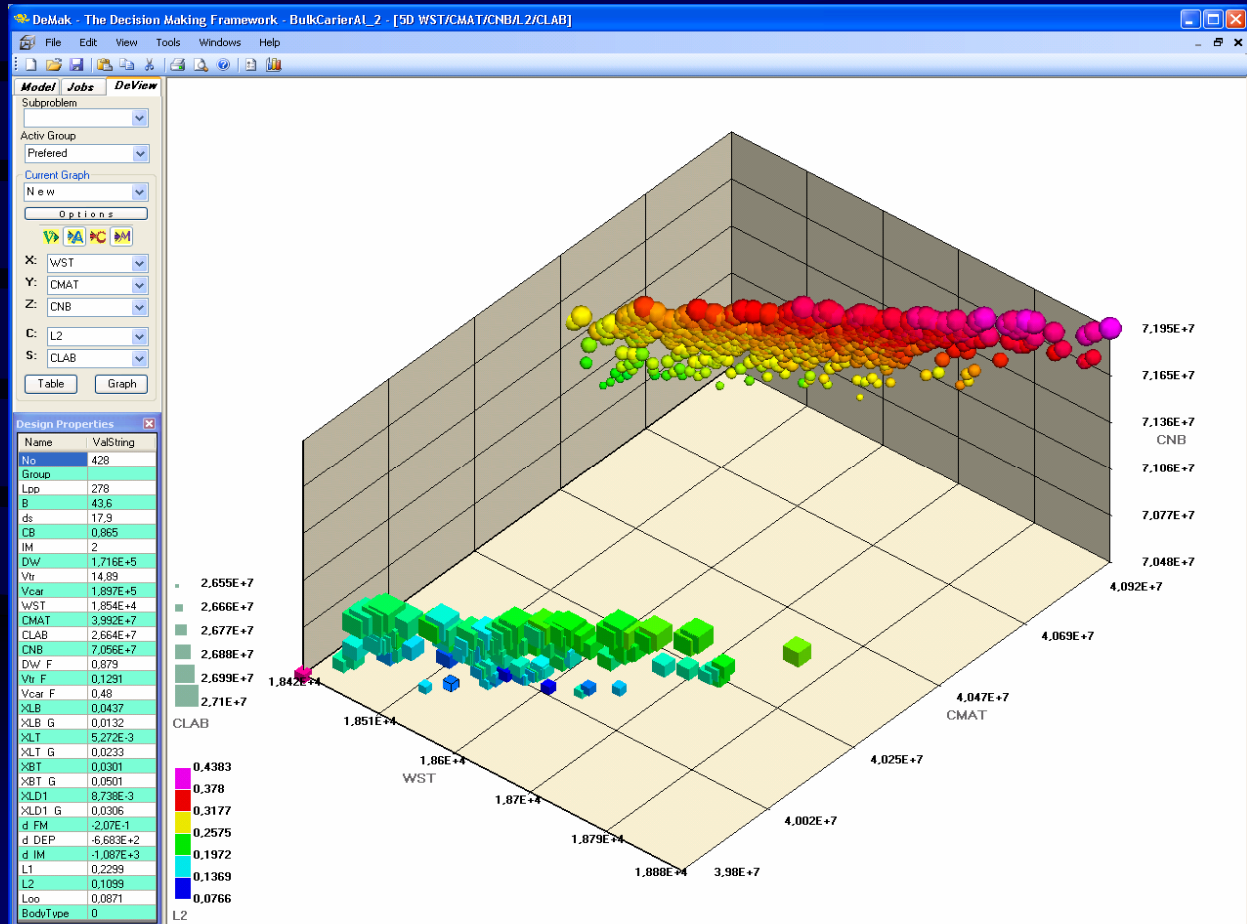
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Optimization Procedure

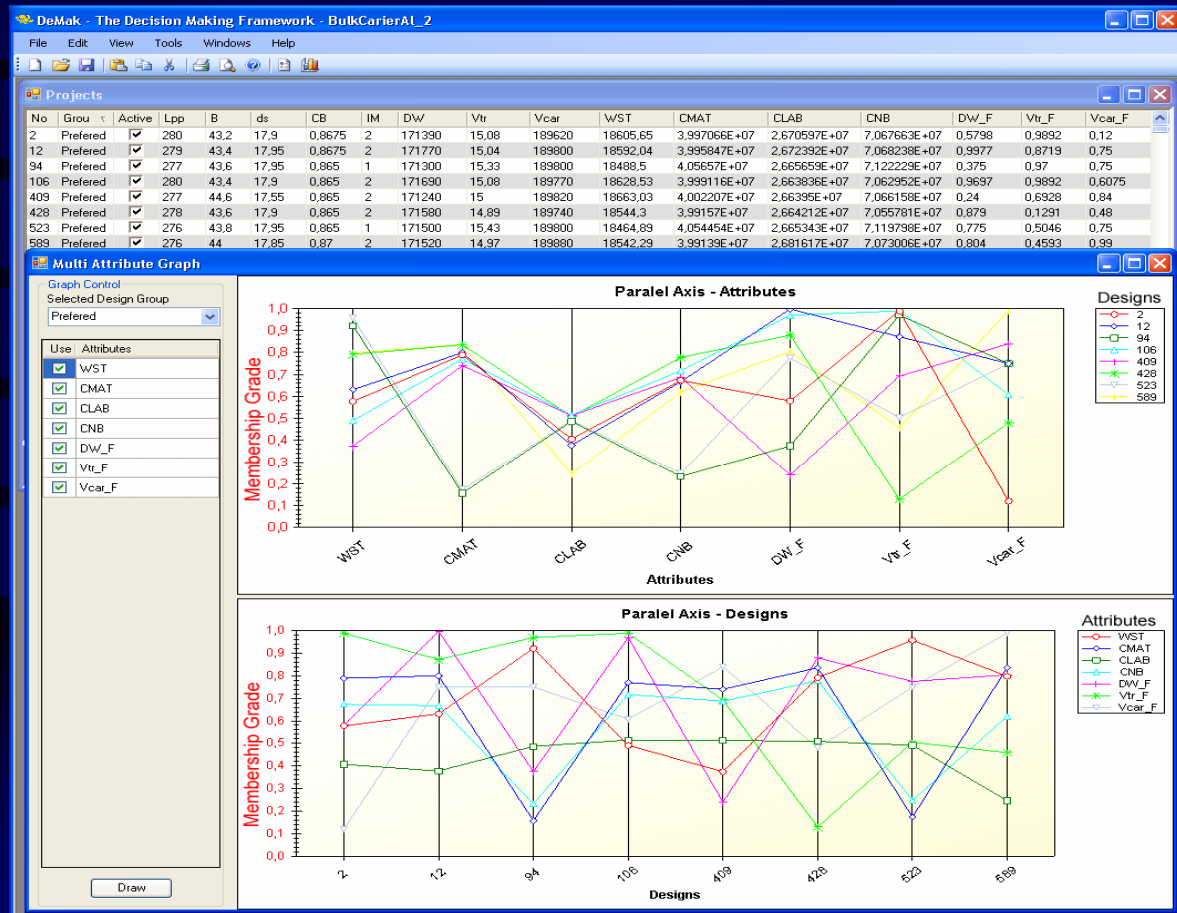


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CASE STUDY in SHIP CONCEPT DESIGN OF HANDYMAX PRODUCT TANKER



Subjective decision making using parallel axes



CONCLUSIONS

The case studies have proved the following points:

- **Increased deadweight + decreased cost of mat. & work**
- **Increased safety due to rational material distribution**
- **Considerable modifications** are **quickly performed** following the head designer's requests.
- **Cost sensitivity study** can be produced **even during negotiations** with ship owner.
- **Full ship analysis** avoids **gross-errors** due to unknown normal and shear stress distribution.

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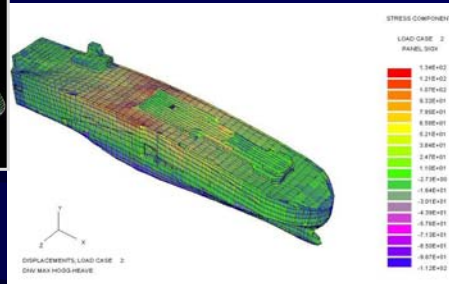
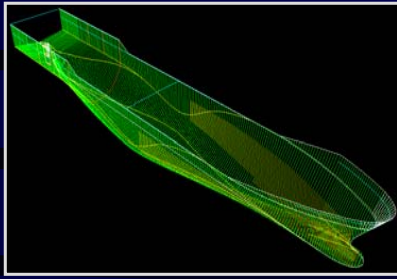
- The **complex full ship macroelement model** can be generated simultaneously with class. documentation **starting from general arrangement**.
- Structural modeling and loadcase selection should **start as soon as possible** and **follow, support and simplify the decision making** to the designer.

Modern design procedure is a necessity rather than an option and FMENA is interested in participating in projects on

development of advanced software for ship design and

its application to inovative ship types.

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